

## 1. A Few Remarks

A huge work has been devoted to the study of the behavior of solutions to

$$-\varepsilon^2 \Delta u + V(x)u = f(x, u) \quad \text{in } \mathbb{R}^3$$

as  $\varepsilon$  goes to zero, where  $V$  is a suitable potential function. Typically, there exists a family of solutions  $u_\varepsilon$  which exhibits a spike shape around the local minima of the function  $V(x)$  and decays elsewhere as  $\varepsilon$  goes to zero. See the works of Ambrosetti, Malchiodi, Del Pino, Felmer, Wei, etc., and the references therein.

Among the others, a physical motivation comes from *nonlinear optics*, in particular in the study of the pulse in a *single mode* optical fiber.

But optical fibers are actually *bimodal* due to *birefringence effects* which tend to split a pulse into *two pulses* in the two polarization directions.

Menyuk (1987) showed that the two polarization components in a birefringence optical fiber are governed by the 1D system (standing waves)

$$\begin{cases} -u_{xx} + u = |u|^2u + b|v|^2u & \text{in } \mathbb{R}, \\ -v_{xx} + \omega^2v = |v|^2v + b|u|^2v & \text{in } \mathbb{R}, \end{cases} \quad \phi(x, t) = e^{i\omega_1^2 t}u(x), \quad \psi(x, t) = e^{i\omega_2^2 t}v(x),$$

where  $\omega^2 = \omega_2^2/\omega_1^2$  and  $b \geq 0$  is a constant depending on the *anisotropy of the fiber*.

- great physical interest <sup>1</sup>, but few rigorous general results;
- radially and decay known by the work of Busca-Sirakov (JDE, 2000);
- $b = 0$ : two copies of a single nonlinear Schrödinger equation;
- $b = 1$ : also known as the Manakov system;
- $b \neq 1$ : the situation gets pretty tough;
- if  $u, v$  are solutions to  $-u_{xx} + u = |u|^2u$  and  $-v_{xx} + \omega^2v = |v|^2v$ , then the couples  $(u, 0)$  and  $(0, v)$  are solutions known as *scalar solitary waves*;
- the existence of a ground state solution  $(u, v) \neq (0, 0)$  has been proved by concentration compactness by Cipelatti-Zumpichiatti (Nonlinear Anal, 2000);
- when is a ground state solution  $(u, v)$  a *true-vector soliton*, that is  $u > 0$  and  $v > 0$ ? <sup>2</sup>

<sup>1</sup> ▶ N. Akhmediev, A. Ankiewicz, *Solitons, Nonlinear pulses and beams*, Chapman & Hall, London, 1997

<sup>2</sup> ▶ A. Ambrosetti, E. Colorado, *Bound and ground states of coupled nonlinear Schrödinger equations*, to appear 2005.

▶ A. Ambrosetti, E. Colorado, *Standing waves of some coupled nonlinear Schrödinger equations*, to appear 2005.

▶ L.A. Maia, E. Montefusco, B. Pellacci, *Positive solutions for a weakly coupled nonlinear Schrödinger system*, preprint 2005.

Let  $\varepsilon > 0$  and  $b > 0$ . Motivated by the above physical observations, we consider the system of two weakly coupled nonlinear Schrödinger equations

$$\begin{cases} -\varepsilon^2 \Delta u + V(x)u = u^3 + bv^2u & \text{in } \mathbb{R}^3, \\ -\varepsilon^2 \Delta v + W(x)v = v^3 + bu^2v & \text{in } \mathbb{R}^3, \end{cases} \quad (S_\varepsilon)$$

in the semiclassical limit.

- The (normalized) limiting system

$$\begin{cases} -\Delta u + u = u^3 + bv^2u & \text{in } \mathbb{R}^3, \\ -\Delta v + v = v^3 + bu^2v & \text{in } \mathbb{R}^3, \end{cases}$$

lacks of uniqueness, in general. For instance, if  $b = 1$  and  $U$  denotes the unique solution to  $-\Delta U + U = U^3$  in  $\mathbb{R}^3$ , then the pairs

$$\{(\cos(\theta)U, \sin(\theta)U) : 0 \leq \theta \leq \pi/2\}$$

are ground state solutions. If  $b < 1$ , the system admits the ground state solutions  $(0, U)$  and  $(U, 0)$ . In the case  $b > 1$ , we suspect that the system admits a unique ground state.

- Unfortunately this produces difficulties, for instance it is not possible to generalize the approaches of Ambrosetti-Badiale-Cingolani, Wang, etc. to the problem.

- In the scalar (single peaked) case, the techniques of del Pino and Felmer (CoV 1996) *does not require uniqueness* assumptions on the limiting problem.

It is based on a suitable *penalization*  $\tilde{J}_\varepsilon$  of the functional  $J_\varepsilon$  associated with the problem outside the region where the potential functions achieve the minimum, so that the critical points  $(u_\varepsilon, v_\varepsilon)$  of  $\tilde{J}_\varepsilon$  are actually solutions to the original problem with the desired features.

- We need a vectorial penalization. In general *truncation* with cut-off functions *does not work* (cannot control many of the needed estimates).
- Due to the particular structure of the nonlinearity,

$$F(u, v) = \frac{1}{4}(|u|^4 + 2b|uv|^2 + |v|^4),$$

for  $\gamma > 0$  to be chosen small enough, the idea is to *replace*  $F$  by:

$$\chi(x)F(s) + (1 - \chi(x)) \begin{cases} \frac{1}{4}(|s|^4 + 2b|st|^2 + |t|^4) & \text{if } |s|^4 + 2b|st|^2 + |t|^4 \leq \gamma^2 \\ \frac{\gamma}{2} \sqrt{|s|^4 + 2b|st|^2 + |t|^4} - \frac{\gamma^2}{4} & \text{if } |s|^4 + 2b|st|^2 + |t|^4 \geq \gamma^2, \end{cases}$$

being  $\chi = \chi_{B(p,r)}$  for some  $r$  and for  $p$  local minimum of the potentials, i.e.

$$V(p) = \inf_{\xi \in B(p,r)} V(\xi) < \min_{\xi \in \partial B(p,r)} V(\xi),$$

$$W(p) = \inf_{\xi \in B(p,r)} W(\xi) < \min_{\xi \in \partial B(p,r)} W(\xi).$$

## 2. Existence of Solutions (Attractive Case)

Let us set

$$\mathcal{H} = \{(u, v) \in H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) : \int_{\mathbb{R}^3} V(x)u^2 + W(x)v^2 < \infty\}.$$

The following result provides the desired family of spike solutions <sup>3</sup>

**Theorem 1.** *Assume that  $V$  and  $W$  are continuous on  $\mathbb{R}^3$  and there exists  $\alpha > 0$  with*

$$V(x) \geq \alpha, \quad W(x) \geq \alpha, \quad \text{for all } x \in \mathbb{R}^3.$$

*Furthermore, assume that there exist  $p \in \mathbb{R}^3$  and  $r > 0$  such that*

$$\begin{aligned} V(p) &= \inf_{B(p,r)} V < \min_{\partial B(p,r)} V, \\ W(p) &= \inf_{B(p,r)} W < \min_{\partial B(p,r)} W. \end{aligned}$$

*Then, for every  $\varepsilon > 0$  sufficiently small, the system*

$$\begin{cases} -\varepsilon^2 \Delta u + V(x)u = u^3 + bv^2u & \text{in } \mathbb{R}^3 \\ -\varepsilon^2 \Delta v + W(x)v = v^3 + bu^2v & \text{in } \mathbb{R}^3 \end{cases}$$

*admits a nontrivial nonnegative solution  $(u_\varepsilon, v_\varepsilon) \in \mathcal{H}$  such that:*

(a)  $u_\varepsilon + v_\varepsilon$  admits exactly one local maximum point  $x_\varepsilon \in B(p, r)$  with

$$\lim_{\varepsilon \rightarrow 0} V(x_\varepsilon) = \inf_{B(p,r)} V \quad \text{or} \quad \lim_{\varepsilon \rightarrow 0} W(x_\varepsilon) = \inf_{B(p,r)} W ;$$

(b) there exist  $\Lambda_1, \Lambda_2 > 0$  such that, for every  $x \in \mathbb{R}^3$ ,

$$u_\varepsilon(x) + v_\varepsilon(x) \leq \Lambda_1 \exp \left\{ -\Lambda_2 \frac{|x - x_\varepsilon|}{\varepsilon} \right\};$$

(c) assuming that  $b \in (0, b_p)$ , where

$$b_p = \sqrt[4]{\max \left\{ \frac{W(p)}{V(p)}, \frac{V(p)}{W(p)} \right\}},$$

*then the following dichotomy holds:*

$$\text{either} \quad \begin{cases} \lim_{\varepsilon \rightarrow 0} u_\varepsilon(x_\varepsilon) > 0, \\ \lim_{\varepsilon \rightarrow 0} v_\varepsilon(x_\varepsilon) = 0, \end{cases} \quad \text{or} \quad \begin{cases} \lim_{\varepsilon \rightarrow 0} u_\varepsilon(x_\varepsilon) = 0, \\ \lim_{\varepsilon \rightarrow 0} v_\varepsilon(x_\varepsilon) > 0. \end{cases}$$

*In particular, if  $V = W$ , the dichotomy holds for every  $b \in (0, 1)$ .*

E. Montefusco, B. Pellacci, M. Squassina, *Semiclassical asymptotic analysis for weakly coupled nonlinear Schrödinger systems*, 2005.

<sup>3</sup>We deal with the **attractive** case  $b > 0$ , for the **repulsive** case  $b < 0$  see the recent work of A. Pomponio, Coupled nonlinear Schrödinger systems with potentials, preprint (2005). See also J. Wei, T.-C. Lin, Spikes in two coupled nonlinear Schrödinger equations, ANIHPC **22** (2005) for the case of **constant potentials**.

### 3. *Some Open Stuff*

- Case  $p \neq q$  with

$$\inf_{B(p,r)} V < \min_{\partial B(p,r)} V, \quad \inf_{B(q,r)} W < \min_{\partial B(q,r)} W;$$

- Case of multi-peak solutions (try new approach of Jeanjean requiring no uniqueness?);
- Case of singular (single/multi-polar) potentials;
- Case of potentials vanishing at  $\infty$ ;
- Tentative proof of uniqueness for:

$$\left\{ \begin{array}{ll} -\Delta \xi + \xi = \xi^3 + b\zeta^2\xi & \text{in } \mathbb{R}^3, \\ -\Delta \zeta + \zeta = \zeta^3 + b\xi^2\zeta & \text{in } \mathbb{R}^3, \\ \xi > 0, \zeta > 0 & \text{in } \mathbb{R}^3, \\ \xi, \zeta \text{ radial, ground state,} & \\ b > 1. & \end{array} \right.$$

#### 4. On Least Energy Functions

Contrary to the scalar case with power nonlinearity, we cannot in general derive an explicit representation of the so called ground energy function, defined as

$$\Sigma(p) = \inf_{(u,v) \in \mathcal{N}_p} I_p(u, v),$$

where  $I_p$  is the functional associated with the limiting system

$$\begin{cases} -\Delta u + V(p)u = u^3 + bv^2u & \text{in } \mathbb{R}^3, \\ -\Delta v + W(p)v = v^3 + bu^2v & \text{in } \mathbb{R}^3, \end{cases}$$

and  $\mathcal{N}_p$  is the Nehari manifold.

*Since the limiting problem lacks of uniqueness, then the ground energy function  $\Sigma$  may lack of regularity and representation formulas.*

#### 5. Scalar Observations

Consider the singularly perturbed equation

$$-\varepsilon^2 \Delta u + u = f(x, u) \quad \text{in } \mathbb{R}^n, \quad u > 0 \quad \text{in } \mathbb{R}^n, \quad (P_\varepsilon)$$

and, for every fixed  $p \in \mathbb{R}^n$ , the limiting autonomous equation

$$-\Delta u + u = f(p, u) \quad \text{in } \mathbb{R}^n, \quad u > 0 \quad \text{in } \mathbb{R}^n. \quad (P_0)$$

There are (classical) choices of  $f(x, u)$  such that the *ground energy function*  $\Sigma$

$$\Sigma(p) = \inf_{\phi \in \mathcal{N}_p} I_p(\phi), \quad I_p(u) = \frac{1}{2} \int_{\mathbb{R}^n} |\nabla u|^2 + u^2 - \int_{\mathbb{R}^n} F(p, u)$$

is  $C^1$ -smooth with an explicit formula. For instance, for some  $\Gamma > 0$ ,

$$\Sigma(p) = \Gamma \frac{V^{\frac{q+1}{q-1} - \frac{n}{2}}(p)}{K^{\frac{2}{q-1}}(p)}, \quad \text{in the case } f(x, u) = K(x)u^q, \quad 1 < q < \frac{n+2}{n-2}.$$

This  $\Sigma$  admits **representation**, is **smooth** (as  $V, K$  are) and rules the concentration:<sup>4</sup>

$$\forall \{u_\varepsilon\} \text{ concentrating at } p \quad \Rightarrow \quad \nabla \Sigma(p) = 0$$

$$\nabla \Sigma(p) = 0 \text{ and } p \text{ is nondegenerate} \quad \Rightarrow \quad \exists \{u_\varepsilon\} \text{ concentrating at } p.$$

This follows by exploiting the **uniqueness of solutions** up to translations of  $(P_0)$ . **If not?**

<sup>4</sup>► X. Wang, B. Zeng, *On concentration of positive bound states of nonlinear Schrödinger equations with competing potential functions*, SIAM J. Math. Anal. **28** (1997), 633–655.

► A. Ambrosetti, A. Malchiodi, S. Secchi, *Multiplicity results for some nonlinear Schrödinger equations with potentials*, Arch. Rational Mech. Anal., **159** (2001), 253–271.

## 6. Nonuniqueness

As known, the *uniqueness feature* for

$$-\Delta u + u = f(p, u) \quad \text{in } \mathbb{R}^n, \quad u > 0 \quad \text{in } \mathbb{R}^n.$$

is a *delicate matter*, it is currently available only under *rather restrictive assumptions* on  $f$ . For (other, limiting) systems (of interest for the study of the corresponding singularly perturbed problem) the situation is *even worse*, e.g.:

$$\begin{cases} -\Delta \xi + \xi = \zeta^q, & \text{in } \mathbb{R}^3, \\ -\Delta \zeta + \zeta = \xi^p, & \text{in } \mathbb{R}^3, \\ \xi > 0, \zeta > 0, & \text{in } \mathbb{R}^3, \end{cases} \quad \begin{cases} -\Delta \xi + \xi = \xi^3 + b\zeta^2\xi & \text{in } \mathbb{R}^3, \\ -\Delta \zeta + \zeta = \zeta^3 + b\xi^2\zeta & \text{in } \mathbb{R}^3, \\ \xi > 0, \zeta > 0 & \text{in } \mathbb{R}^3, \end{cases}$$

No uniqueness result available.

## 7. In General

For many scalar and vectorial Lagrangians, there holds:

- $\Sigma$  is a *locally Lipschitz continuous* function (what beyond the  $\text{Lip}_{\text{loc}}$  ?);
- $\Sigma$  has *representation formulas for the left and right derivatives*  $\left(\frac{\partial \Sigma}{\partial z_j}\right)^-(p)$ ,  $\left(\frac{\partial \Sigma}{\partial z_j}\right)^+(p)$ .

Motivated by these facts, recently, some conditions for locating the concentration points for  $P_\varepsilon$  in presence of a nonlinearity  $f$ , not necessarily a power, have been investigated.

$$\forall \{u_\varepsilon\} \text{ of minimal energy solutions concentrating at } p \quad \Rightarrow \quad 0 \in \partial_C \Sigma(p).$$

where  $\partial_C$  denotes the *Clarke subdifferential* of  $\Sigma$ , see,

S. Secchi, M. Squassina, *On the location of concentration points for singularly perturbed elliptic equations*, Adv. Differential Equations **9** (2004), 221–239.

S. Secchi, M. Squassina, *On the location of spikes for the Schrödinger equation with electromagnetic field*, Commun. Contemp. Math. **9** (2005), 251–268.

## 8. Sufficiency?

$$0 \in \partial_C \Sigma(p), \text{ plus more} \quad \stackrel{?}{\Rightarrow} \quad \exists \{u_\varepsilon\} \text{ of minimal energy solutions concentrating at } p.$$

## 9. Back to the Schrödinger System

Let us set, for  $b > 0$ ,

$$\mathcal{O}_b = \left\{ p \in \mathbb{R}^3 : \max \left\{ \frac{W(p)}{V(p)}, \frac{V(p)}{W(p)} \right\} \geq b^4 \right\}, \quad \Gamma = \frac{1}{4} \|U\|_{L^4(\mathbb{R}^3)}^4,$$

being  $U$  the unique ground state solution to  $-\Delta u + u = u^3$  in  $\mathbb{R}^3$ .  $J_\varepsilon$  denotes the functional associated with the system. Consider the sets:

$$\mathcal{E} = \left\{ p \in \mathbb{R}^3 : \text{there exists a sequence of solutions } (u_\varepsilon, v_\varepsilon) \text{ of } (S_\varepsilon) \text{ with } u_\varepsilon(p + \varepsilon x) + v_\varepsilon(p + \varepsilon x) \rightarrow 0 \text{ as } |x| \rightarrow \infty \text{ uniformly w.r.t. } \varepsilon, \text{ and } \varepsilon^{-3} J_\varepsilon(u_\varepsilon, v_\varepsilon) \rightarrow \Sigma(p) \text{ as } \varepsilon \rightarrow 0 \right\},$$

$$\mathcal{E}_V = \left\{ p \in \mathcal{O}_b : \text{there exists a sequence of solutions } (u_\varepsilon, v_\varepsilon) \text{ of } (S_\varepsilon) \text{ with } u_\varepsilon(p) \geq \delta \text{ for some } \delta > 0, u_\varepsilon(p + \varepsilon x) + v_\varepsilon(p + \varepsilon x) \rightarrow 0 \text{ as } |x| \rightarrow \infty \text{ uniformly w.r.t. } \varepsilon, \text{ and } \varepsilon^{-3} J_\varepsilon(u_\varepsilon, v_\varepsilon) \rightarrow \Gamma \sqrt{V(p)} \text{ as } \varepsilon \rightarrow 0 \right\},$$

$$\mathcal{E}_W = \left\{ p \in \mathcal{O}_b : \text{there exists a sequence of solutions } (u_\varepsilon, v_\varepsilon) \text{ of } (S_\varepsilon) \text{ with } v_\varepsilon(p) \geq \delta \text{ for some } \delta > 0, u_\varepsilon(p + \varepsilon x) + v_\varepsilon(p + \varepsilon x) \rightarrow 0 \text{ as } |x| \rightarrow \infty \text{ uniformly w.r.t. } \varepsilon, \text{ and } \varepsilon^{-3} J_\varepsilon(u_\varepsilon, v_\varepsilon) \rightarrow \Gamma \sqrt{W(p)} \text{ as } \varepsilon \rightarrow 0 \right\},$$

and

$$\mathcal{E}_\Sigma = \mathcal{E} \setminus \mathcal{O}_b.$$

If  $\partial_C$  stands for the Clarke subdifferential, we shall also set:

$$\begin{aligned} \text{Crit}(V) &= \{p \in \mathcal{O}_b : \nabla V(p) = 0\}, \\ \text{Crit}(W) &= \{p \in \mathcal{O}_b : \nabla W(p) = 0\}, \\ \text{Crit}_C(\Sigma) &= \{p \in \mathbb{R}^3 \setminus \mathcal{O}_b : 0 \in \partial_C \Sigma(p)\}. \end{aligned}$$

We recall a useful property of ground states justifying the introduction of  $\mathcal{O}_b$ .

**Proposition 1.** *Let  $p \in \mathcal{O}_b$  and assume that  $(\varphi_p, \psi_p)$  is a least energy solution to*

$$\begin{cases} -\Delta u + V(p)u = u^3 + bv^2u & \text{in } \mathbb{R}^3, \\ -\Delta v + W(p)v = v^3 + bu^2v & \text{in } \mathbb{R}^3. \end{cases}$$

*Then either  $\varphi_p = 0$  and  $\psi_p \neq 0$  or  $\varphi_p \neq 0$  and  $\psi_p = 0$ .*

## 10. Necessary Conditions

**Theorem 2.** Assume that  $V, W \in C^1(\mathbb{R}^3)$  with

$$|\nabla V(x)| \leq \beta e^{\gamma|x|} \quad \text{and} \quad |\nabla W(x)| \leq \beta e^{\gamma|x|},$$

for all  $x \in \mathbb{R}^3$  and for some constants  $\beta > 0$  and  $\gamma \geq 0$ .

Then  $\Sigma$  is locally Lipschitz continuous and the following facts hold:

(a) if  $V \neq W$ , then  $\mathcal{E}_V \cap \mathcal{E}_W = \emptyset$  and

$$\mathcal{E} = \mathcal{E}_V \cup \mathcal{E}_W \cup \mathcal{E}_\Sigma,$$

where

$$\mathcal{E}_V \times \mathcal{E}_W \times \mathcal{E}_\Sigma \subset \text{Crit}(V) \times \text{Crit}(W) \times \text{Crit}_C(\Sigma).$$

(b) if  $V \neq W$  are bounded, there exists  $b_\star > 0$  with

$$\mathcal{E} = \mathcal{E}_V \cup \mathcal{E}_W \quad \text{for all } b \in (0, b_\star),$$

where

$$\mathcal{E}_V \times \mathcal{E}_W \subset \text{Crit}(V) \times \text{Crit}(W).$$

In particular, if  $V = W$ , then

$$\mathcal{E} = \mathcal{E}_V \subset \text{Crit}(V) \quad \text{for all } b \in (0, 1).$$