

Shape Analysis

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 - J. Bauer
 - R. Biber
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Shape Analysis

[Jones and Muchnick 1981]

- Determine the possible shapes of a dynamically allocated data structure at a given program point

Programs and Properties

- Dynamically allocated memory
- Recursive data structures
- Recursive procedures
- Concurrency
- Memory safety
- Preservation of Data structure invariants
- Partial correctness
- Termination
- Linearizability

Outline

- Shape abstractions in a nutshell
- Computing transformers
- Heap decomposition

Representing Concrete Stores by Logical Structures

- Parametric vocabulary
- Heap
 - Locations \approx Individuals
 - Program variables \approx Unary relations
 - Fields \approx Binary relations

Representing Concrete Stores by Logical Structures

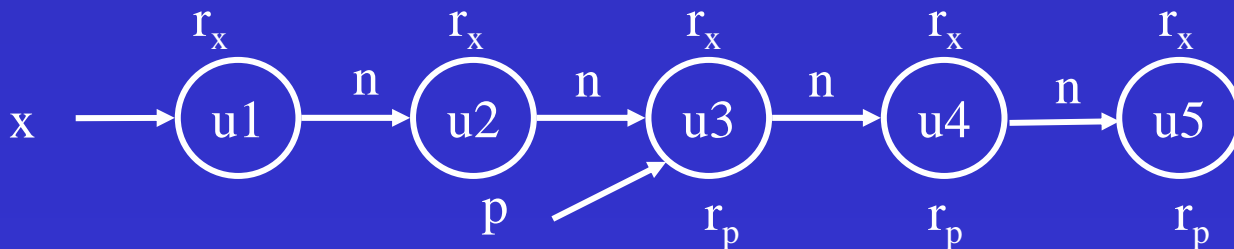
– $U = \{u1, u2, u3, u4, u5\}$

– $x = \{u1\}$, $p = \{u3\}$

– $n = \{\langle u1, u2 \rangle, \langle u2, u3 \rangle, \langle u3, u4 \rangle, \langle u4, u5 \rangle\}$

– $r_x = \{u1, u2, u3, u4, u5\}$

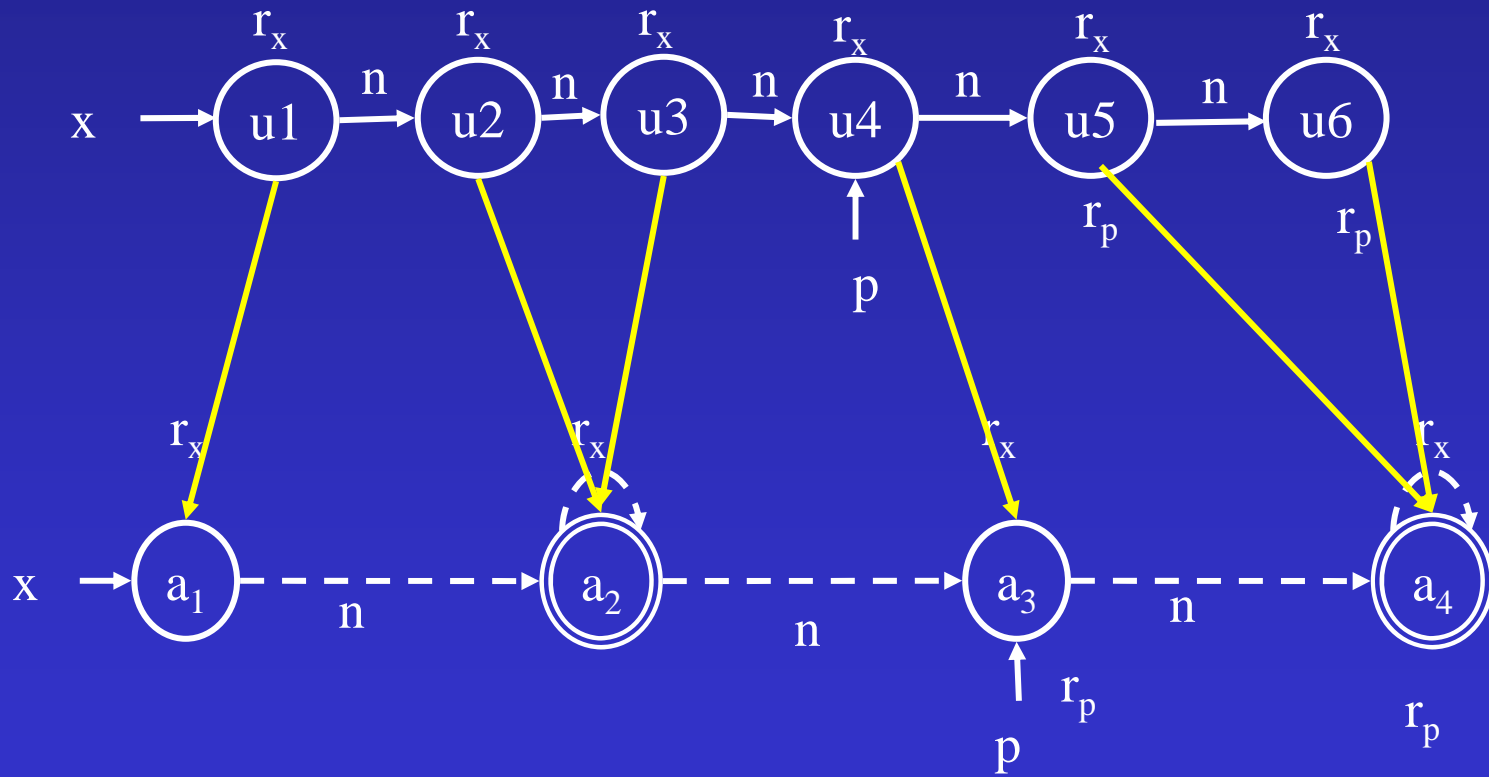
– $r_p = \{u3, u4, u5\}$



Representing Abstract Stores by 3-Valued Logical Structures

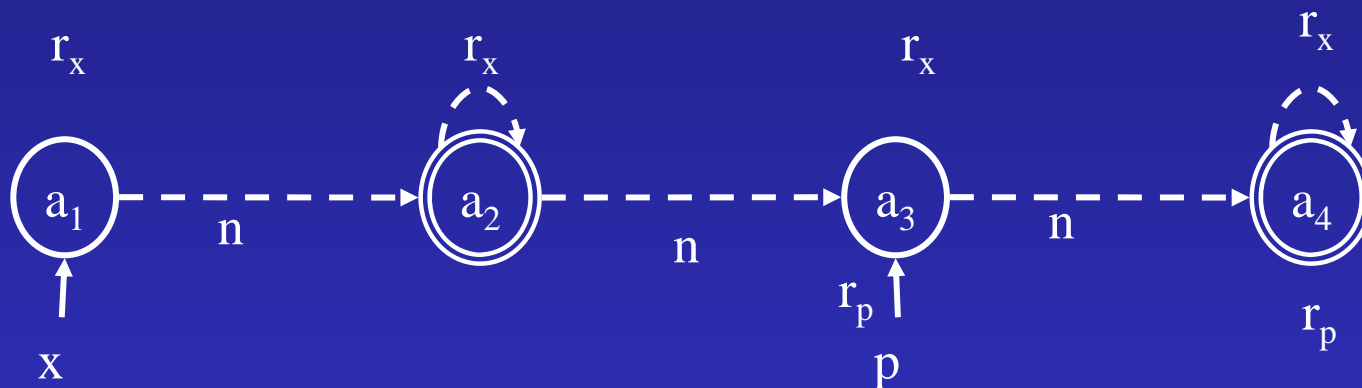
- A join semi-lattice: $0 \sqcup 1 = 1/2$
- $\{0, 1, 1/2\}$ values for relations

Canonical Abstraction



Canonical Abstractions as Formulas

[Yorsh'03, Kuncak'04, Wies'07]



$$\forall v: (x(v) \wedge r_x(v) \wedge \neg p(v) \wedge \neg r_p(v)) \vee$$

$$(\neg x(v) \wedge r_x(v) \wedge \neg p(x) \wedge \neg r_p(v)) \vee$$

$$(\neg x(v) \wedge r_x(v) \wedge p(v) \wedge r_p(v)) \vee$$

$$(\neg x(v) \wedge r_x(v) \wedge \neg p(v) \wedge r_p(v))$$

$$\forall v: r_x(v) \Leftrightarrow \exists w: x(w) \wedge n^*(w, v)$$

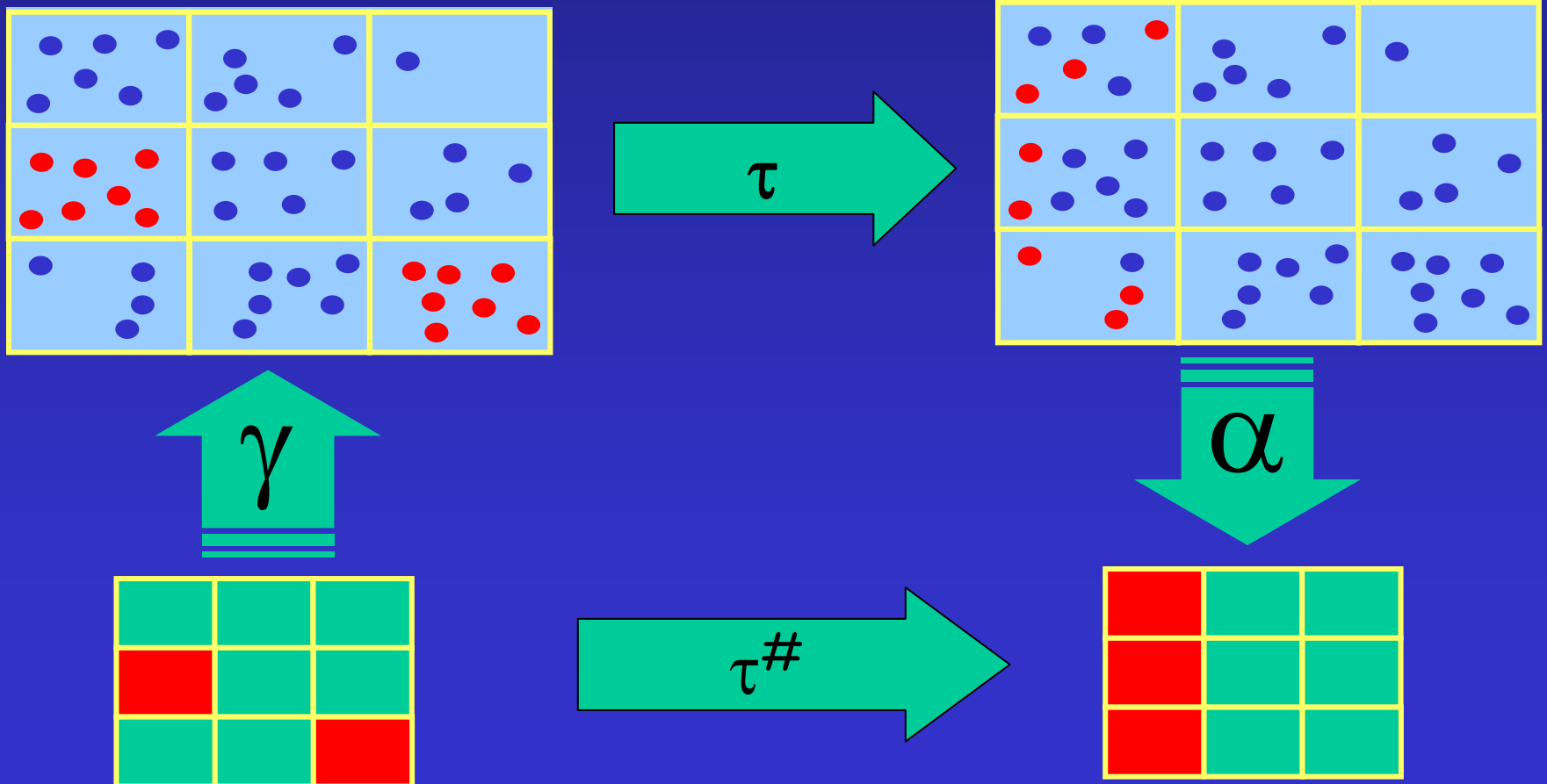
$$\forall v: r_p(v) \Leftrightarrow \exists w: p(w) \wedge n^*(w, v)$$

Canonical Abstraction

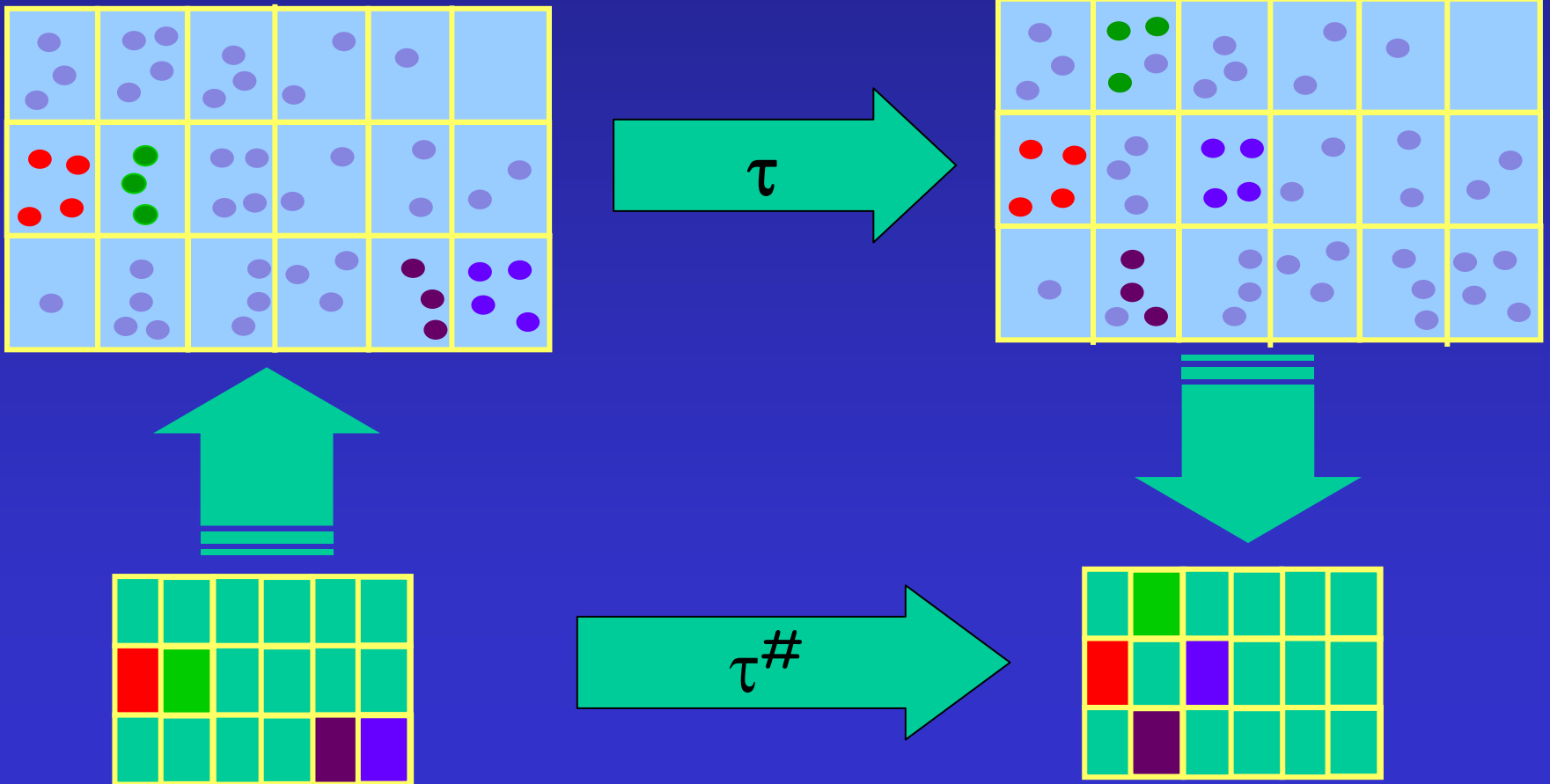
- Limited form of quantified invariants
 - quantifier alternation only in instrumentation
- Not a static memory partition
 - The same memory location can be represented by different abstract nodes in different shape graphs

Most Precise Abstract Transformer

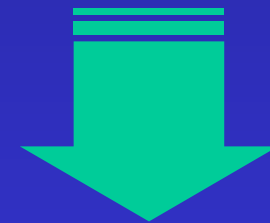
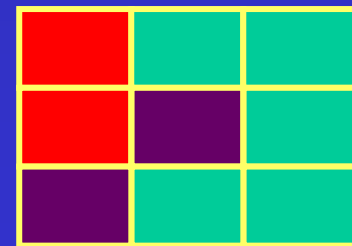
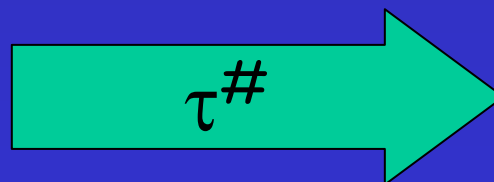
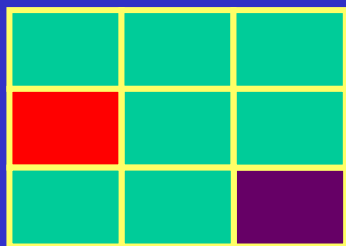
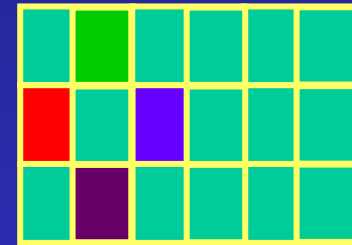
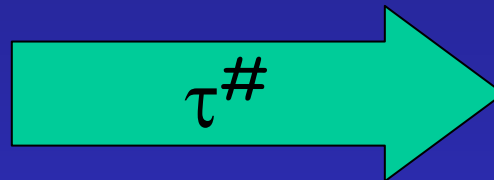
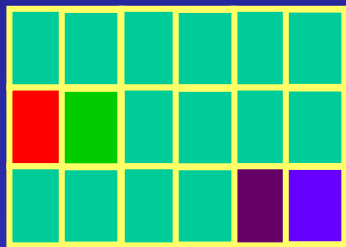
[Cousot, Cousot POPL 1979]



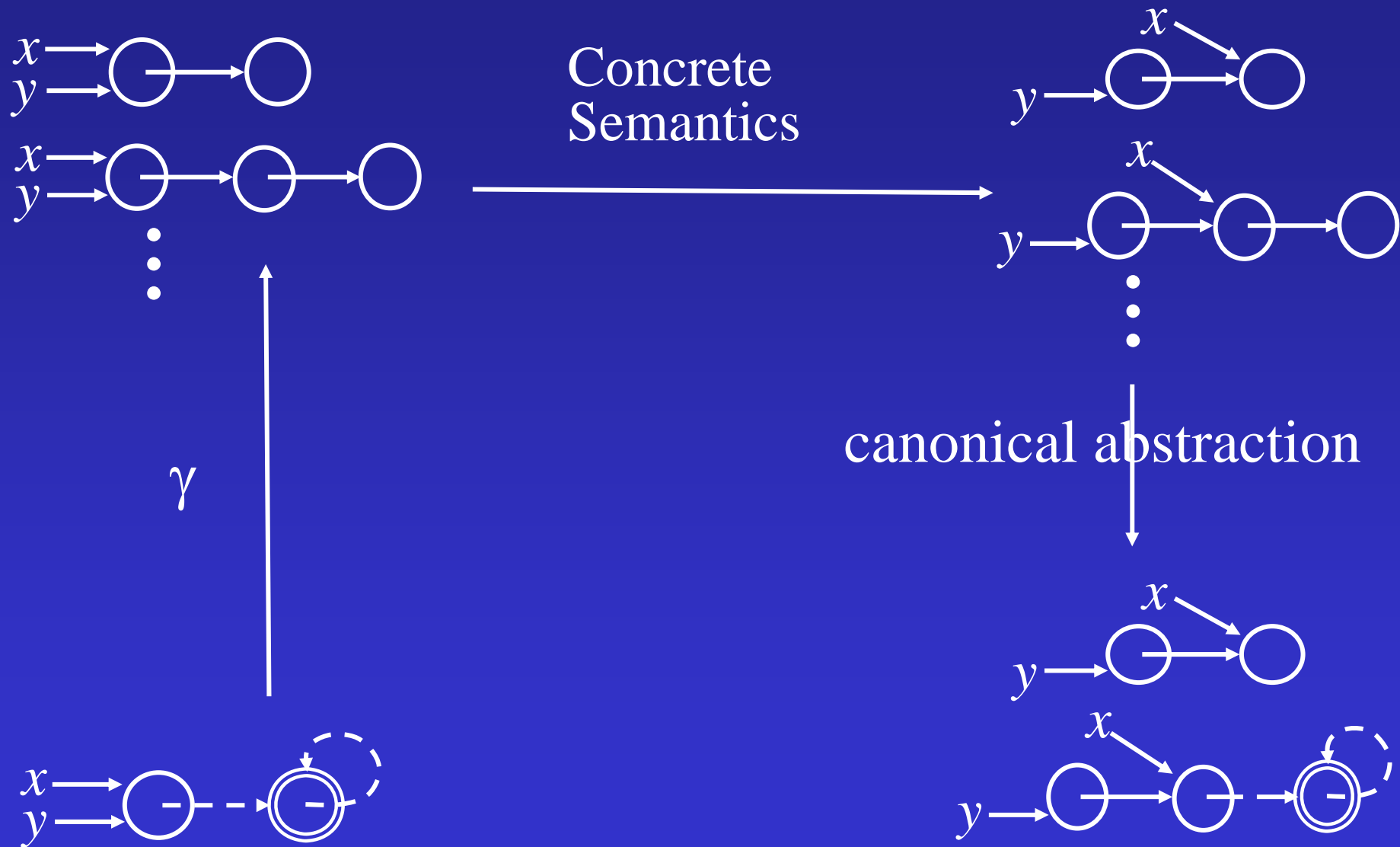
Partial Concretization



Partial Concretization



Best Transformer ($x = x \rightarrow n$)



Partial Concretization

- Employed in other shape analysis algorithms
[Distefano, TACAS'06, Evan, SAS'07, POPL'08]
- Soundness is immediate
- Can even guarantee precision under certain conditions [Lev-Ami, VMCAI'07]
- Locally refine the abstract domain per statement

Heap Decomposition for Concurrent Shape Analysis

Joint work with

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MSR India

J. Berdine
MSR Cambridge

Main Results

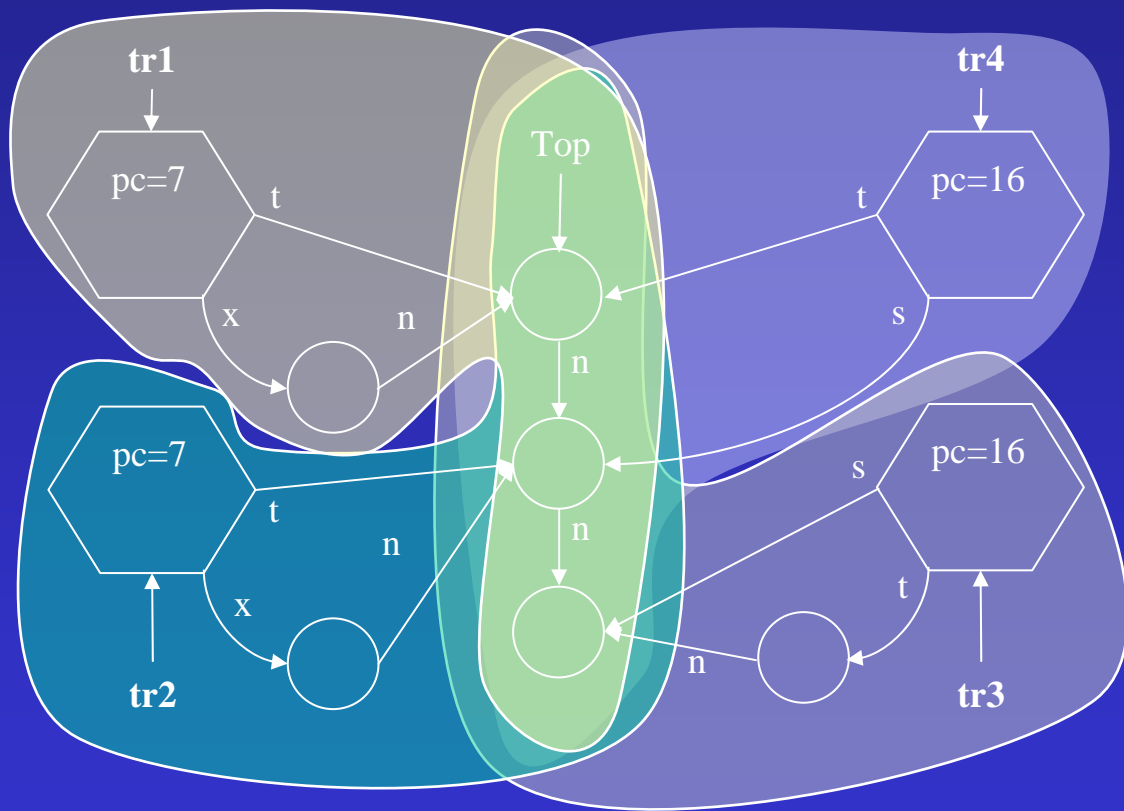
- New parametric abstraction for heaps
 - Heap decomposition + Cartesian product
- Exponential state space reduction
- Implementation in HeDec (Generalizes TVLA)
 - Heap Decomposition + Canonical abstraction
- Used to prove interesting properties of heap-manipulating programs with fine-grained parallelism
 - Linearizability

Treiber's Non-blocking Stack

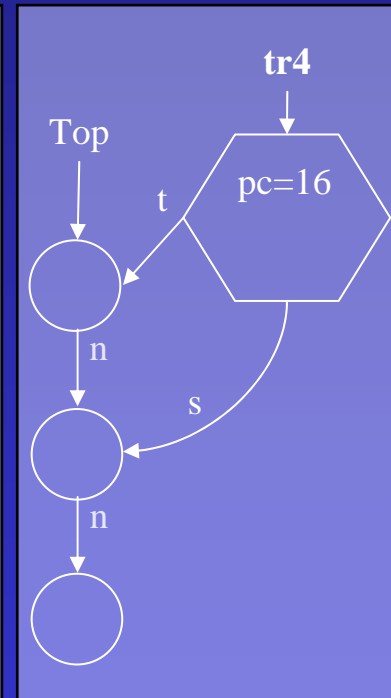
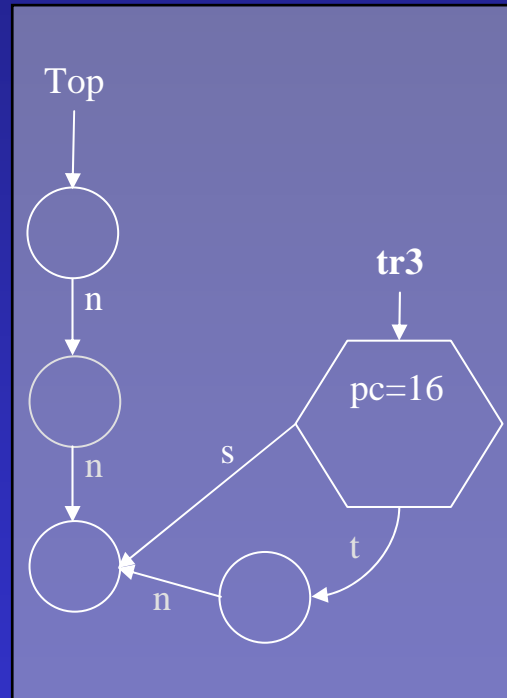
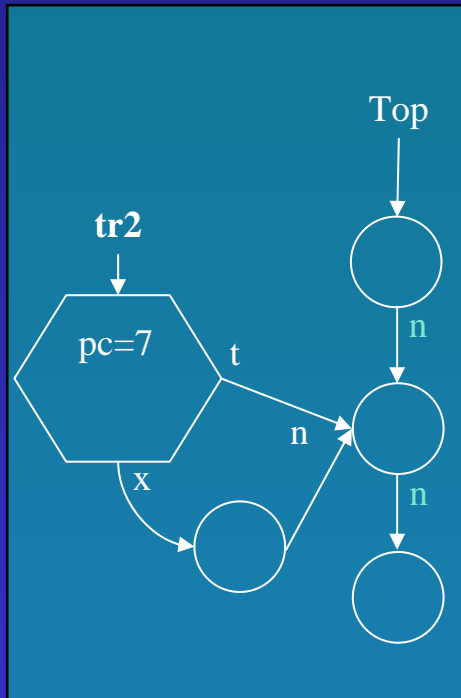
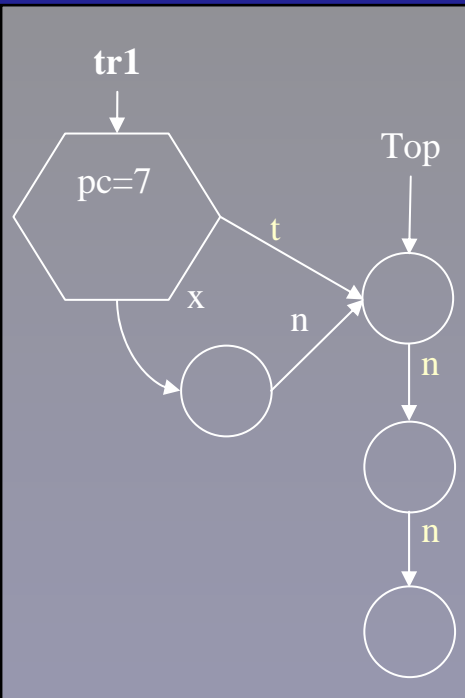
```
[1] void push(Stack *S, data_type v) {
[2]     Node *x = alloc(sizeof(Node));
[3]     x->d = v;
[4]     do {
[5]         Node *t = S->Top;
[6]         x->n = t;
[7]     } while (!CAS(&S->Top,t,x));
[8] }

[9] data_type pop(Stack *S){
[10]     do {
[11]         Node *t = S->Top;
[12]         if (t == NULL)
[13]             return EMPTY;
[14]         Node *s = t->n;
[15]         data_type r = s->d;
[16]     } while (!CAS(&S->Top,t,s));
[17]     return r;
[18] }
```

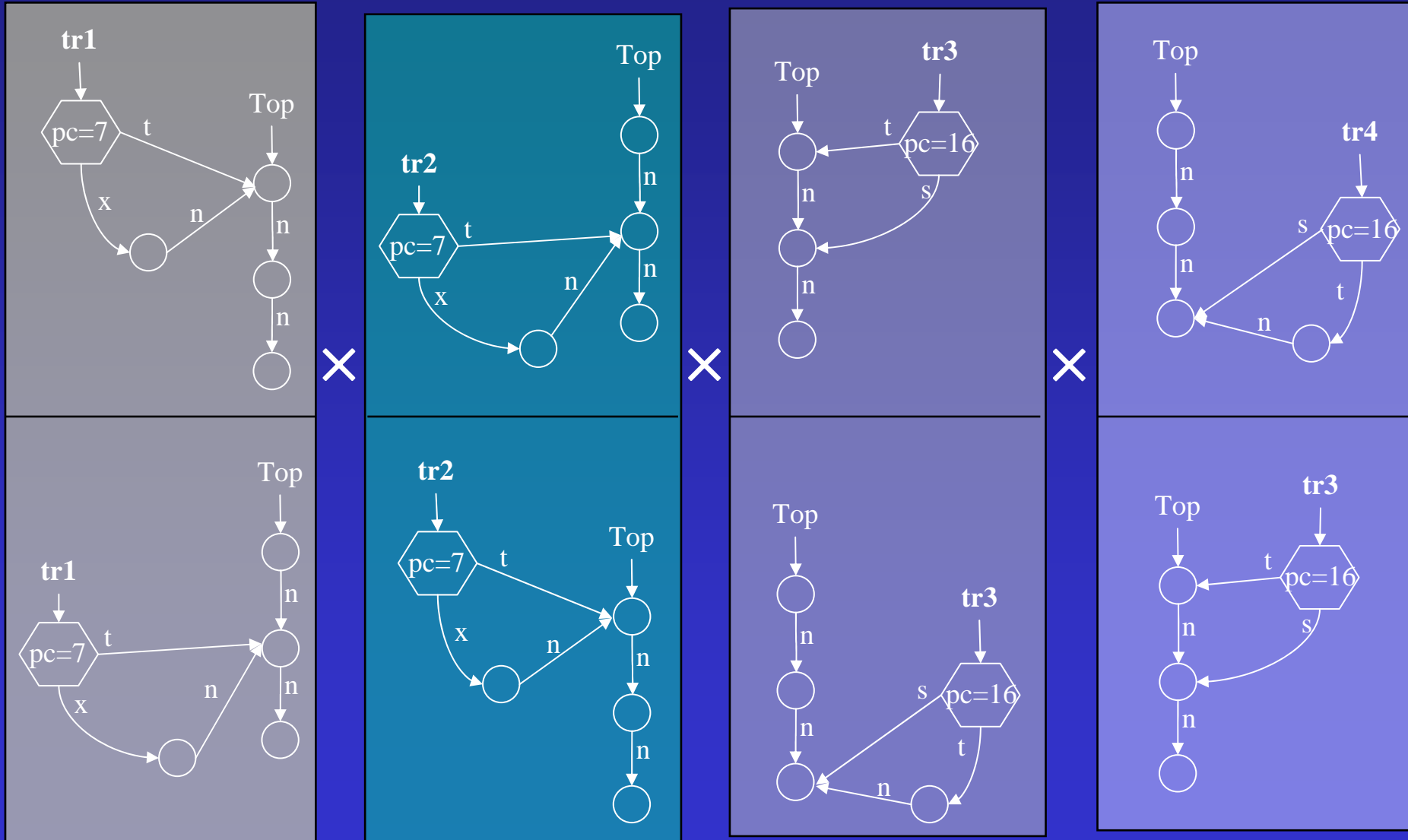
Full State



Sub-states

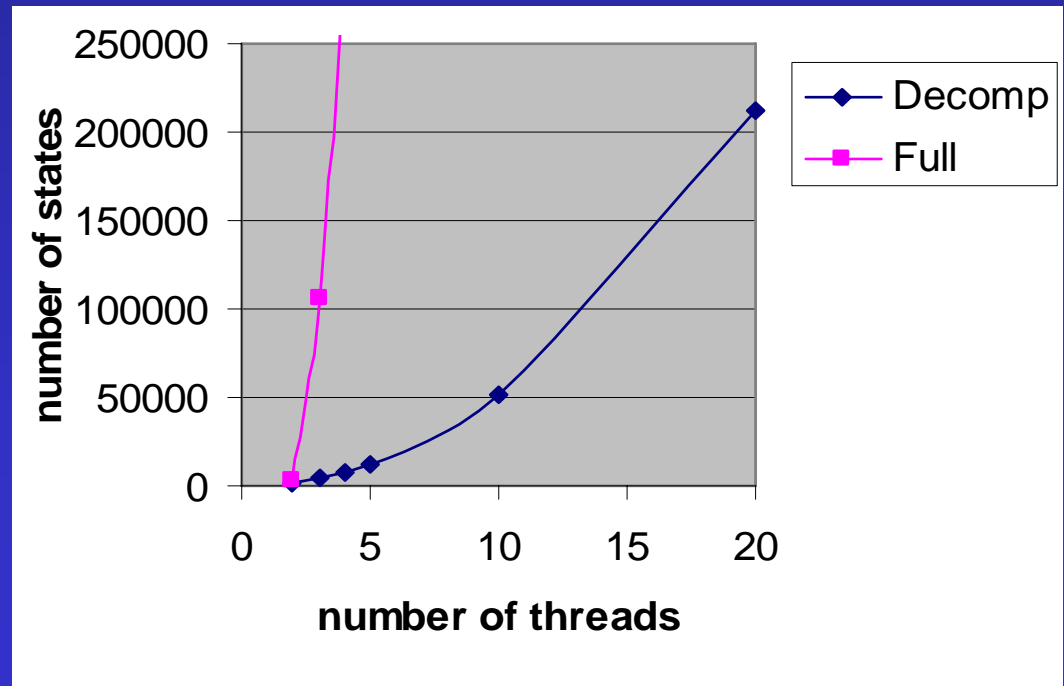
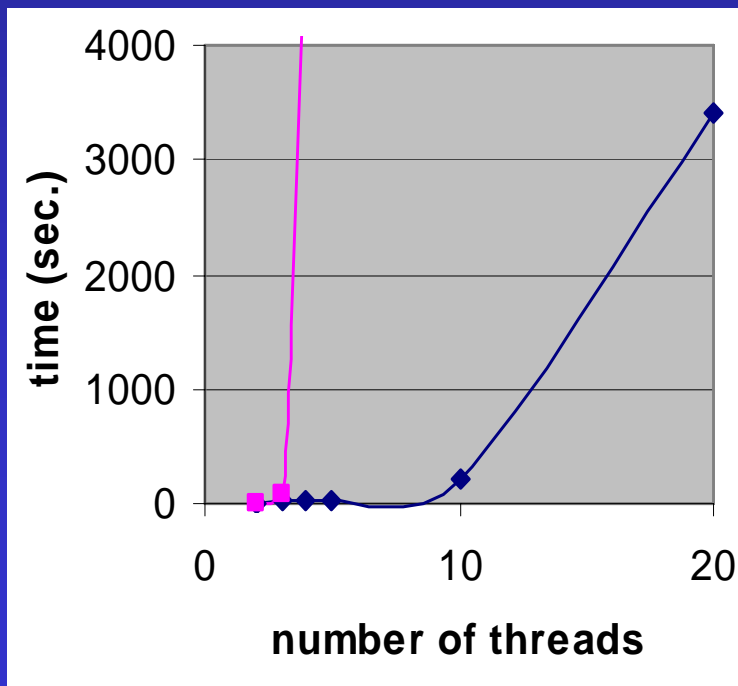


Cartesian Product of Sub-states



Empirical Results

- Exponential time/space reduction
 - Non-blocking stack + linearizability



and...

More information from

<http://www.cs.tau.ac.il/~rumster>

Thank you Cousot for

- Establishing the right mindset
- Galois Connections
- Semantic reductions
- Domain constructors

Summary

- Shape analysis is an interesting abstract interpretation problem
 - Handles unbounded memory
 - Partially disjunctive abstractions
- Partial concretization is useful for transformers
- Heap decomposition is useful for scalability
 - Generalizes thread-modular analysis
- Limited forms of quantified invariants can be utilized to prove interesting properties