

Local search algorithms

AIMA sections 4.1,4.2

Summary

Local search
algorithms

- ◇ Hill-climbing
- ◇ Simulated annealing
- ◇ Genetic algorithms (briefly)
- ◇ Local search in continuous spaces (very briefly)

Iterative improvement algorithms

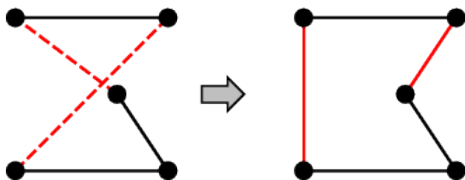
Local search algorithms

- ◇ In many optimization problems, **path** is irrelevant; the goal state itself is the solution
- ◇ Then state space = set of “complete” configurations; find **optimal** configuration, e.g., TSP, etc.
or, find configuration satisfying constraints, e.g., n-Queens
- ◇ In such cases, can use **iterative improvement** algorithms; keep a single “current” state, try to improve it
- ◇ Constant space, suitable for online as well as offline search

Example: Travelling Salesperson Problem

Local search
algorithms

Start with any complete tour, perform pairwise exchanges

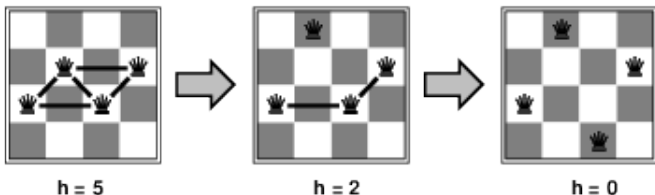


Variants of this approach get within 1% of optimal very quickly with thousands of cities

Example: n -queens

Local search algorithms

- ◇ Put n queens on an $n \times n$ board with no two queens on the same, row, column, or diagonal
- ◇ Move a queen to reduce number of conflicts



Almost always solves n -queens problems almost instantaneously for very large n , e.g., $n = 1\text{million}$

Hill-climbing (or gradient ascent/descent)

“Like climbing Everest in thick fog with amnesia”

function Hill-Climbing(*problem*) **returns** a state that is a local maximum

inputs: *problem*, a problem

local variables: *current*, a node

neighbor, a node

current \leftarrow Make-Node(*problem*.Initial-State)

loop do

neighbor \leftarrow a highest-valued successor of *current*

if *neighbor*.Value \leq *current*.Value **then return**
current.State

end if

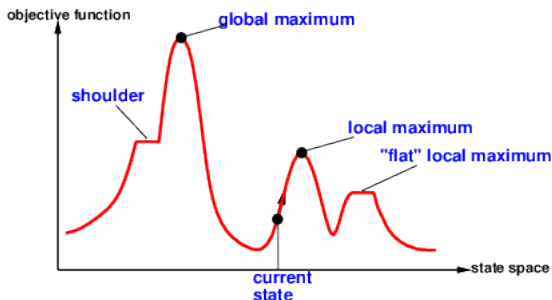
current \leftarrow *neighbor*

end

Hill-climbing contd.

Local search
algorithms

Useful to consider state space landscape



Random-restart hill climbing overcomes local maxima—trivially complete

Random sideways moves 😊 escape from shoulders 🙄 loop on flat maxima

Simulated Annealing

Local search
algorithms

- Inspired by statistical mechanics
- Idea: escape local maxima by allowing some “bad” moves, **but gradually decrease their frequency**
- Allow more random moves at the beginning
 - we can reach zones with better solutions
- Diminish probability of having a random move towards the end
 - refine search around a good solution

Simulated annealing (pseudo-code)

function Simulated-Annealing(*problem*, *schedule*) **returns** a solution state

inputs: *problem*, a problem

schedule, a mapping from time to “temperature”

local variables: *current*, a node

next, a node

T, a “temperature” controlling prob. of downward steps

current \leftarrow Make-Node(*problem*.Initial-State)

for $t \leftarrow 1$ **to** ∞ **do**

T \leftarrow *schedule*(t)

if $T = 0$ **then return** *current*

next \leftarrow a randomly selected successor of *current*

$\Delta E \leftarrow$ *next*.Value – *current*.Value

if $\Delta E > 0$ **then** *current* \leftarrow *next*

else *current* \leftarrow *next* only with probability $e^{\Delta E / T}$

Properties of simulated annealing

Local search algorithms

At fixed “temperature” T , state occupation probability reaches Boltzman distribution

$$p(x) = \alpha e^{\frac{E(x)}{kT}}$$

T decreased slowly enough \implies always reach best state x^*
because $e^{\frac{E(x^*)}{kT}} / e^{\frac{E(x)}{kT}} = e^{\frac{E(x^*) - E(x)}{kT}} \gg 1$ for small T

Is this necessarily an interesting guarantee??

- ◇ Devised by Metropolis et al., 1953, for physical process modelling
- ◇ Widely used in VLSI layout, airline scheduling, etc.

Local beam search

Local search algorithms

Idea: keep k states instead of 1; choose top k of all their successors

Not the same as k searches run in parallel!

Searches that find good states recruit other searches to join them

Problem: quite often, all k states end up on same local hill

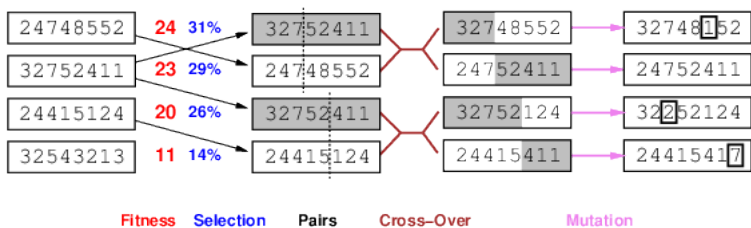
Idea: choose k successors randomly, biased towards good ones

Observe the close analogy to natural selection!

Genetic algorithms

Local search algorithms

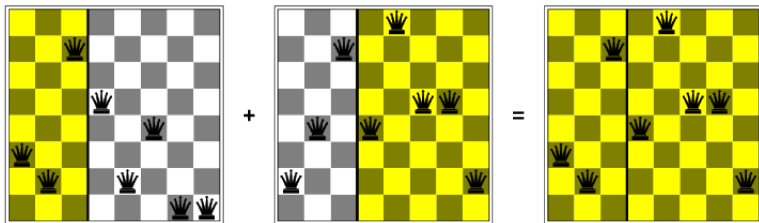
= stochastic local beam search + generate successors from **pairs** of states



Genetic algorithms contd.

Local search algorithms

GAs require states encoded as strings (GPs use **programs**)
Crossover helps **iff substrings are meaningful components**



GAs \neq evolution: e.g., real genes encode replication machinery!

Continuous state spaces

Suppose we want to site three airports in Romania:

- 6-D state space defined by $(x_1, y_1), (x_2, y_2), (x_3, y_3)$
- objective function $f(x_1, y_1, x_2, y_2, x_3, y_3) =$
sum of squared distances from each city to nearest airport

Discretization methods turn continuous space into discrete space,

e.g., **empirical gradient** considers $\pm\delta$ change in each coordinate

Gradient methods compute

$$\nabla f = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial y_1}, \frac{\partial f}{\partial x_2}, \frac{\partial f}{\partial y_2}, \frac{\partial f}{\partial x_3}, \frac{\partial f}{\partial y_3} \right)$$

to increase/reduce f , e.g., by $\mathbf{x} \leftarrow \mathbf{x} + \alpha \nabla f(\mathbf{x})$

Sometimes can solve for $\nabla f(\mathbf{x}) = 0$ exactly (e.g., with one city).

Newton–Raphson (1664, 1690) iterates $\mathbf{x} \leftarrow \mathbf{x} - \mathbf{H}_f^{-1}(\mathbf{x}) \nabla f(\mathbf{x})$

to solve $\nabla f(\mathbf{x}) = 0$, where $\mathbf{H}_{ij} = \partial^2 f / \partial x_i \partial x_j$

Exercise: Local Search for the 4-Queens problem

Consider the 4-Queens problem. Assume the evaluation function is the number of pairs of queens that attack each other. Assume initial state is (1234)

- What is the current score for the initial state
- Write down the values of all successor states for this initial state
- Implement a simple program that computes the next best state(s) for your hill-climbing approach
- Trace a possible execution of a (deterministic) hill-climbing approach
- Comment on optimality of final state
- **sol:** [eserc1LocalSearch.m](#)

Exercise: Local Beam Search for the 4-Queens problem

Local search algorithms

Consider the 4-Queens problem and the deterministic hill climbing approach described above. Assume $k = 3$ and initial states are: (1234), (2222), (3333).

- Trace execution of a **parallel** search
sol: [eserc2Parallel.m](#)
- Trace the execution of a **beam** search
sol: [eserc2BeamSearch.m](#)