

AI Lab - Exam

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Listing 1: Upgrade the repository

```
cd gym-ai-lab  
git pull  
pip3 install --user -l --no-deps -e .
```

In case of problems you can just delete the “gym-ai-lab” folder and clone it again.

Listing 2: Upgrade the repository

```
rm -rf gym-ai-lab  
git clone https://github.com/SaricVr/gym-ai-lab  
cd gym-ai-lab  
pip3 install --user -l --no-deps -e .
```

How to Submit Your Solutions

Create a .zip file named MATRICOLA_AI_Exam.zip, e.g., VR487172_AI_Exam.zip containing the following:

- exercise1.txt with:
 - ▶ The output printed by your code: path and stats for each algorithm
 - ▶ The answer to the questions
- exercise2.txt with:
 - ▶ The output printed by your code: the final policy for each algorithm
 - ▶ The answer to the questions
- rewards.png: the chart representing the rewards obtained by the algorithms during learning
- lengths.png: the chart representing the lengths of the learning episodes for the algorithms
- a folder named “code” containing the code you run to obtain the results

Note: the code you provide must execute without any errors! Therefore, include any additional file/procedure needed

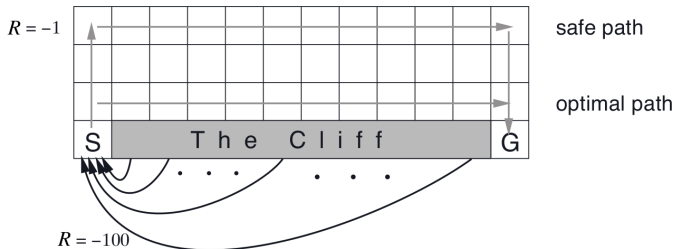
Send the zip file to:

`alessandro.farinelli@univr.it`

with *subject*: esame laboratorio IA <MATRICOLA>

- Each answer must explicitly refer to the corresponding exercise
- Each answer must be explicitly motivated referring to the results obtained by your code
- Results must be reproducible: if you refer to a result your code is not producing in output, or that is different from your code's output, the answer will be invalidated
- Remember to report the output of your code in the .txt along with the answers

Exercise 1 - Environment



Actions

- 0 - U
- 1 - R
- 2 - D
- 3 - L

Environment taken from Sutton and Barto

Environment name in gym: "CliffWalkingExam2018-v0"

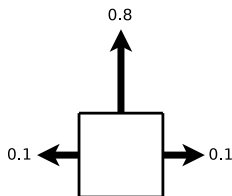
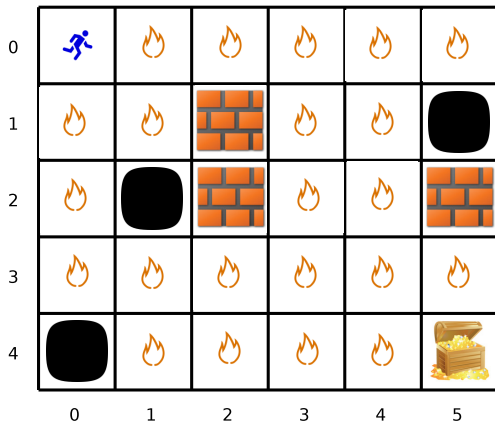
State which search-based algorithm¹ (considering both tree search and graph search versions) you would choose to solve this problem. Motivate your choice and show a print-out of the path and statistics (max number of node in memory and number of expanded node) for the algorithms you considered.

Warning

Given the size of the environment, **DO NOT USE** the tree search version of BFS, UCS and Greedy.

¹Use the L_1 norm as distance heuristic

Exercise 2 - Environment



Action dynamics:

- 0.8 chosen direction
- 0.1 directions at 90° w.r.t. the chosen one

Rewards:

- -0.04 for each lava cell
- -10 for the black pit
- +10 for the gold treasure

Environment name in gym: "LavaFloorExam2018-v0"

State which Reinforcement Learning algorithm you would choose to solve this problem. Motivate your choice and show the following charts:

- ① rewards obtained during the learning phase for each algorithm
- ② lengths of the learning episodes for each algorithm

Consider only the following versions for the RL algorithms

- Model-Based with initial policy of 0 - "L" for every state;
- Q-Learning *epsilon*-greedy;
- SARSA *epsilon*-greedy.

Note: the environment is stochastic! Execute your code multiple times in order to verify the consistency of the results

Use the following parameters (where they apply):

- 1 number of episodes = 1000
- 2 max number of steps for each episode (`ep_limit`) = 200
- 3 max iterations for value iteration = 200
- 4 convergence threshold for value iteration (δ) = 1^{-3}
- 5 discount factor (γ) = 0.9, learning rate (α) = 0.6
- 6 probability of sub-optimal action (ϵ) = 0.1
- 7 rolling window² = 20

²The smoothing function in `[session3/rl.utils.rolling]`