

# Consistency Enforcing and Constraint Propagation: Path consistency and i-consistency

# Summary

Consistency  
Enforcing  
and  
Constraint  
Propagation:  
Path  
consistency  
and  
i-consistency

Path  
Consistency  
i-consistency

- Path Consistency
- i-consistency

# Path consistency

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## Basic Concepts

- $x, y, z, R_{x,y}, R_{y,z}, R_{x,z}$
- Arc consistency: every consistent value of  $x$  can be extended to  $y$
- Path consistency every consistent couple of values for  $x, y$  can be extended to  $z$

# Path consistency: Example

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## Example (Path Consistency)

- $x, y, z, D = \{1, 2\}$
- $R_{x,y} = \{(1, 1)(2, 2)\}, R_{x,z} = \{(1, 1)(1, 2)(2, 1)\}, R_{y,z} = \{(1, 1)(2, 2)\}$

# Path consistency: Definition

## Definition (Path Consistency for $x, y$ relative to $z$ )

- Couple of variables  $x, y$  and a third variable  $z$
- Constraints  $R_{x,y}, R_{x,z}, R_{y,z}$  (if a constraint does not exist all values are possible)
- $x, y$  is path consistent w.r.t.  $z$  iff:
  - $\forall \langle a, b \rangle \in R_{x,y} \wedge a \in D_x \wedge b \in D_y$
  - $\exists c \in D_z \mid \langle a, c \rangle \in R_{x,z} \wedge \langle b, c \rangle \in R_{y,z}$
- Graphically: a triangle in the matching diagram

# Why Path consistency is important

## importance of path consistency

If path consistency does not hold for  $x = a, y = b$  relative to  $z$  then  $\langle a, b \rangle$  can not be part of any solution

- If we fix  $a, b$  we can not find any value for  $z$
- But we need to assign  $z$  and the solution must satisfy all constraints

# Path consistency for problems

## Path Consistency for $\mathcal{R}$

$\mathcal{R}$  path consistent iff

- for every couple of variables  $x, y$  and every other variable  $z$
- $x, y$  path consistent relative to  $z$

## Path Consistency for $R_{x,y}$ relative to $z$

Constraint  $R_{x,y}$  is path consistent relative to  $z$

- every couple in  $R_{x,y}$  is path consistent relative to  $z$

# Enforcing path consistency

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## Enforcing Path Consistency for $\mathcal{R}$

If  $\mathcal{R}$  is not path consistent

- exists a couple of variables  $x = a, y = b$  that can not be extended to  $z$
- $x = a, y = b$  can not be part of any solution
- but we can not remove  $a, b$  from their respective domains!



# Enforcing path consistency: Example

## Example (Enforcing Path Consistency)

- Variables:  $x, y, z$  Domains:  $D = \{1, 2\}$
- Constraints  $R_{x,y} = \{(1, 1)(1, 2)(2, 1)\}$ ,  $R_{x,z} = \{(1, 1)(2, 1)(2, 2)\}$ ,  $R_{y,z} = \{(1, 2)(2, 1)(2, 2)\}$
- $x = 1, y = 1$  can not be extended to any value of  $z$  but we have solutions with  $x = 1$  and  $y = 1$
- Removing  $x = 1$  (or  $y = 1$ ) could make other solutions disappear

# Enforcing path consistency

## Enforcing Path Consistency for $\mathcal{R}$

Given  $x = a, y = b$  not path consistent relative to  $z$

- we eliminate  $\langle a, b \rangle$  from  $R_{x,y}$
- $R_{x,y}$  now is path consistent with respect to  $z$
- we did not remove solutions:
  - $a, b$  could not be in any solution
  - $a \in D_x$  and  $b \in D_y$  can still be used for other solutions
- Simpler problem: do not need to check  $z$  to realise  $a, b$  not a solution

# Enforcing path consistency: Revise-3

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## Revise-3 proc.

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### Algorithm 1 Revise-3( $(x, y), z$ )

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**Require:** A three variable subnetwork over  $x, y, z$ ,  
 $R_{x,y}, R_{y,z}, R_{x,z}$

**Ensure:** Revised  $R_{x,y}$  path consistent relative to  $z$   
**for all**  $\langle a, b \rangle \in R_{x,y}$  **do**  
    **if**  $\neg \exists c \in D_z \mid (a, c) \in R_{x,z} \wedge (b, c) \in R_{y,z}$  **then**  
        delete  $a, b$  from  $R_{x,y}$   
    **end if**  
**end for**

---

Equivalent to  $R_{xy} \leftarrow R_{xy} \cap \pi_{xy}(R_{xz} \bowtie D_z \bowtie R_{zy})$

# Revise-3: Example

## Example (Revise-3)

- Variables:  $x, y, z$  Domains:  $D = \{1, 2\}$
- Constraints  $x \neq y, y \neq z, z \neq x$
- Run  $\text{Revise-3}((x, y), z)$

# Inconsistent problem

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## Inconsistent Problem

If a revise makes a relation ( $R_{x,y}$ ) empty the problem is inconsistent

- We have to assign  $x$  and  $y$
- Every possible assignment will not satisfy  $R_{x,y}$

node/arc consistency	remove values from <b>domains</b>	empty <b>domain</b> → inconsistency
path consistency	remove values from <b>relations</b>	empty <b>relation</b> → inconsistency

# Loosing Path Consistency

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## PC-1

- Removing values from  $R_{x,y}$
- We can loose pathconsistency wherever it depends on  $R_{x,y}$ 
  - between couple  $\langle x,z \rangle$  and  $y$
  - between couple  $\langle y,z \rangle$  and  $x$

# Path Consistency Algorithm

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## PC-1

**Require:**  $\mathcal{R} = \langle X, D, C \rangle$

**Ensure:** A path consistent network equivalent to  $\mathcal{R}$

**repeat**

**for all**  $k \leftarrow 1$  to  $n$  **do**

**for all**  $i, j \leftarrow 1$  to  $n \mid j \neq k \wedge i \neq k \wedge i < j$  **do**

      Revise( $(x_i, x_j), x_k$ );

**end for**

**end for**

**until** no constraint is changed

# PC-1: Example

## Example (Enforcing Path Consistency)

- Variables:  $x_1, x_2, x_3$  Domains:  $D = \{1, 2\}$
- Constraints  $x_1 \neq x_3, x_2 \neq x_3$



# Creating new constraints

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## New constraints

- We can create a new constraint between  $x$  and  $y$  when they share a constraint with another variable  $z$
- We can not have a constraint when two nodes are not connected
- We could have constraint creation even if variables are connected but not directly connected: multiple constraint creation.

# Example

## Example (New constraints)

- $x, y, z; R_{xz}$ 
  - Can we create a new constraint between  $x, y$  ?
- $x, y, z, w; R_{xz}, R_{zw}, R_{wy}$ 
  - Can we create a new constraint between  $x, y$  ?

# PC-1 Computational Complexity

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## Comp. Complexity

- $O(n^5 k^5)$
- Revise for each triplets is  $O(k^3)$
- Each cycle we revise at most  $O(n^3)$  triplets
- Number of cycles is at most  $O(n^2 k^2)$ 
  - Because at each cycle we remove at least one element from one constraint, number of elements in all constraints is  $O(n^2 k^2)$

# Improvements for PC-1

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## Improve PC-1: PC-2

- Can do better than PC-1 (similarly to AC-1)
- We can focus on triplets that might have changed (similarly to AC-3)
- If  $R_{x,y}$  is changed we re-process all triplets involving  $x, y$
- $x, y, z$  with  $z$  any other variable

# Path Consistency Algorithm

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## PC-2

**Require:**  $\mathcal{R} = \langle X, D, C \rangle$

**Ensure:** A path consistent network equivalent to  $\mathcal{R}$

$Q \leftarrow \{ \langle i, k, j \rangle \mid 1 \leq i < j \leq n \wedge 1 \leq k \leq n \wedge k \neq i \wedge k \neq j \}$

**while**  $Q \neq \{ \}$  **do**

    pop  $\langle i, k, j \rangle$  from  $Q$

    Revise( $(x_i, x_j), x_k$ );

**if**  $R_{x_i, x_j}$  changed **then**

$Q \leftarrow Q \cup \{ \langle l, i, j \rangle, \langle l, j, i \rangle \mid 1 \leq l \leq n \wedge l \neq i \wedge l \neq j \}$

**end if**

**end while**

# PC-2 Computational Complexity

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## Comp. Complexity

- $O(n^3 k^5)$
- Revise for each triplets is  $O(k^3)$
- Number of times we process the queue is at most  $O(n^3 k^2)$
- Because we can put back an element at most  $O(k^2)$

# PC-2: Example

## Example (Enforcing Path Consistency)

- Variables:  $x_1, x_2, x_3, x_4$  Domains:  $D = \{1, 2\}$
- Constraints  $x_1 \neq x_2, x_2 \neq x_3, x_3 \neq x_4, x_4 \neq x_1$

# Path consistency: alternative definition

## Path consistency

- $R_{x_i, x_j}$  is path consistent relative to a path of length  $m$  if we can find a sequence of other  $m - 2$  values such that all constraints along the path  $i, i_1, \dots, i_{m-1}, j$  are satisfied.
- if we consider complete graphs the two definitions are the same
- if we consider only **real** path definitions are different



# Inconsistency

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## Inconsistencies when forcing consistency

- When forcing arc or path consistency we can make a domain or a constraint empty, then the problem is inconsistent.
- The opposite is not **always** true... but it is true in some cases
- For this class of problems arc/path consistency ensures consistency of the problem: **tractable cases**
- **Tractable** because they are polynomial

# Not tractable problem: example

## arc/path consistent problem that is inconsistent

- Variables:  $x_1, x_2, x_3, x_4$  Domain:  $D = \{0, 1, 2\}$
- Constraints  
 $x_1 \neq x_2, x_1 \neq x_3, x_1 \neq x_4, x_2 \neq x_3, x_2 \neq x_4, x_3 \neq x_4$
- For every value of every variable (e.g., 0) there is always a different value for another variable (e.g., 2) (arc consistent)
- For every couple of values of two variables (e.g., 0,1) there is always another value of another variable (e.g., 2)
- But we can not find 4 values that are all different in the domain  $\{0, 1, 2\}$

# Arc Consistency and Consistency

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## Why we have local consistency but global inconsistency

- Consider a tree.
- If each node is arc consistent with its children then the problem is arc consistent
- The problem is also **globally consistent**
- This is because siblings will never introduce inconsistency
- **Cycles** are the problem

# Complete case for Arc Consistency

## completeness for arc consistency

An arc (and node) consistent problem is globally consistent iff

- no empty domain
- only binary constraints
- primal graph contains no cycle

Solution algorithm for this type of problems

- Enforce arc consistency
- Recall: no constraint addition  $\rightarrow$  still acyclic
- If no domain is empty
  - Choose a node
  - Choose a value for the node and extend it to all its children
  - Propagate the choice **value propagation**
- Otherwise the problem is inconsistent

# Complete case for Path Consistency

## completeness for path consistency

- A path (and arc and node) consistent problem is consistent iff
  - no empty relation or empty domain
  - only binary constraints
  - **only two values** in the domain
- Even if primal graph has cycles

# i-consistency: general concept

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## Basic ideas

- arc consistency consider sub-network of size 2
- path consistency consider sub-network of size 3
- i-consistency generalisation of this concept for sub-network of size  $i - 1$

# i-consistency

## i-consistency

- Given relation  $R_S$  and a variable  $y$
- $S \subseteq X$ ,  $|S| = i - 1$ ,  $y \notin S$
- $R_S$  is  $i$ -consistent relative to  $y$  iff
  - for every tuple  $t \in R_S$  there is a value  $a_y \in D_y$  such that
  - $(t, a)$  is consistent

# i-consistency for network

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## i-consistent $\mathcal{R}$

- $\mathcal{R}$  is i-consistent iff:
- for any consistent instantiation of  $i - 1$  distinct variables
- there is a value of the  $i$ th values
- such that the  $i$  values satisfy all constraints among them



# i-consistency example

## Example

### 4-Queens problem

- The 4-Queen problem is 2-consistent
- The 4-Queen problem is not 3-consistent
- The 4-Queen problem is not 4-consistent

# strong i-consistency for network

## strong i-consistent $\mathcal{R}$

- $\mathcal{R}$  is strong i-consistent iff:
- $\mathcal{R}$  is j-consistent for any  $j \leq i$
- If  $\mathcal{R}$  is strongly n-consistent then it is globally consistent
- For a globally consistent network we can extend any consistent partial instantiation to a complete instantiation without dead end

# strong i-consistency example

## Example

all 5 equals

- Variables  $X$  con  $|X| \geq 5$ ; Domain:  $D = \{0, 1\}$
- Constraints: allEquals on all subset of **exactly** 5 variables
- This problem is 6-consistent but not 5-consistent

# global consistency

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## strong i-consistent $\mathcal{R}$

- $\mathcal{R}$  is strong i-consistent iff:
- $\mathcal{R}$  is j-consistent for any  $j \leq i$
- If  $\mathcal{R}$  is strongly n-consistent then it is **globally** consistent

# enforcing i-consistency

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## adding constraints to enforce i-consistency

- To enforce i-consistency we might need to add constraints of  $i - 1$  variables
- These constraints record forbidden combinations or **no-good**
- Therefore binary network might become non-binary
- Example: 4-Queens

# Enforcing i-consistency: Revise-i

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## Revise-i proc.

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**Algorithm 2** Revise-i( $(x_1, x_2, \dots, x_{i-1}), x_i$ )

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**Require:** A network  $\mathcal{R}$ , a constraint  $R_S$ , which might be universal

**Ensure:** A constraint  $R_S(S = x_1, x_2, \dots, x_{i-1})$  which is i-consistent relative to  $x_i$

**for all** instantiations  $\bar{a}_{i-1} \in R_S$  **do**

**if**  $\neg \exists a_i \in D_i | (\bar{a}_{i-1}, a_i)$  is consistent **then**

        delete  $\bar{a}_{i-1}$  from  $R_S$

**end if**

**end for**

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# Complexity of Revise-i

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## Revise-i complexity

- Complexity of Revise-i for only binary constraints is  $O(k^i)$
- With general constraint we have  $O(2k^i)$
- We might need to check  $2^i$  constraints
- If  $e$  bounds the constraints then  $O(ek^i)$

# i-Consistency Algorithm

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## i-consistency for networks

**Require:**  $\mathcal{R} = \langle X, D, C \rangle$

**Ensure:** An i-consistent network equivalent to  $\mathcal{R}$

**repeat**

**for all**  $S \subseteq X$  of size  $i - 1$  **do**

**for all**  $x_i$  **do**

      Revise-i( $(S), x_i$ );

**end for**

**end for**

**until** no constraint is changed



# 3-Consistency and Path-Consistency

## 3-Consistency vs. Path Consistency

- On a binary network 3-Consistency = Path-Consistency
- If we have ternary constraints then not the same
- Example:
  - $x, y, z$   $R_{x,y,z} = (0, 0, 0)$
  - Path consistency will do nothing: no binary constraint
  - 3-Consistency: at least add the constraint  
 $R_{x,y} = \langle x, 0 \rangle \langle y, 0 \rangle$