

Consistency Enforcing and Constraint Propagation: Node and Arc Consistency

Summary

Consistency
Enforcing
and
Constraint
Propagation:
Node and
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Consistency

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Techniques

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- Node consistency and Arc Consistency

Solution Techniques for Constraint Network

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Solving Constraint Networks

- Inference:
 - Infer new constraints based on existing ones
 - Eliminate values from variables that do not meet constraints
- Search:
 - Look for a solution trying different values of variables
 - backtracking and similar approaches
 - local search

Backtracking

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general ideas

- Choose a variable x
- list its domain values
- for each value add a constraint $x = v$ and recursively evaluate the rest of the problem

Local Consistency

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general ideas

- Partial assignments can lead to constraint violations
 - We can evaluate a constraint as soon as all variables in its scope are assigned
- We can backtrack as soon as a constraint is not locally consistent

Inference and constraint propagation

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Example (inference)

- Variables: $\{A, B, C\}$
- Domain: $\{0, 1\}$ or true,false
- Constraint: $\{A \rightarrow B, C \rightarrow A, C\}$
- Propagating the constraints we can infer $\{A, B\}$
- Similar reasoning if we know $\{\neg B\}$ holds

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Consistency Methods

- Approximation of inference
 - arc, path and i-consistency
- Generate tighter networks
- Partial assignments can be discarded earlier

Example

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Example (Consistency)

- n-Queen problem
- Minimal network is tighter than original network
- On minimal network finding the solution is **easier**

Tightness and search space

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restricting the searchspace

- Given two **equivalent** network \mathcal{R} and \mathcal{R}'
- if $\mathcal{R}' \subset \mathcal{R}$ (\mathcal{R}' is tighter than \mathcal{R})
- then searching for a solution on \mathcal{R}' is more efficient than searching on \mathcal{R}
- \mathcal{R}' has a smaller search space

Complete inference

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finding solution with no dead end

- We can deduce constraints until:
 - an inconsistency is found
 - or we can derive a solution with depth-first and no backtracking
- but we might need to introduce an exponential number of constraint
- usually it is preferable to introduce a bounded amount of constraints

Consistency approaches

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consistency enforcing

- Given a partial solution of length $i - 1$ we extend the solution to one more variable
- Consistency enforcing:
 - any partial solution of a subnetwork extensible to a surrounding network
 - size of the subnetwork defines different approaches
- Arc-Consistency: from 1 variable to 2
- Path-Consistency: from 2 variables to 3
- l-consistency: from $i-1$ to i

Extending solutions

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consistency and solution extension

- $i-1$ consistency:
 - for any legal value for $i-1$ variables
 - we can find a legal value for any other connected variables.
- A network that is i -consistent for $i = 1, \dots, n$ is globally consistent

Consistency and computational issues

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consistency and computation

- The higher is i the better a search algorithm will behave
- time and space cost to ensure i -consistency is exponential in i
- Trade-off addressed with experimental evaluation

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Example (consistency)

- Variables: $\{X, Y, T, Z\}$, $D_i = 1, 2, 3$
- Constraints: $X < Y, Y = Z, T < Z, X < T, X < 4$

Node consistency

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Node consistency

- Variable x_i , Domain D_i
- x_i is node consistent if **every** value of its domain satisfy **every** unary constraint
- $\forall v \in D_i \forall C = \{ \langle x \rangle, R_{x_i} \} a \in R_{x_i}$

Constraint propagation

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Constraint Propagation

- We modify the constraint network so that:
 - local consistency is satisfied (enforcing consistency)
 - solutions do not change (maintaining equivalence)

Constraint propagation for node consistency

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CP for node consistency

- If a variable x_i is not node consistent:
 - remove all values from D_i that do not satisfy all unary constraints
 - $D'_i = D_i \setminus \{v \mid \exists C = \{ \langle x_i, v \rangle, R_{x_i} \} \wedge v \notin R_{x_i} \}$
- D'_i contains only values that satisfy all unary constraints (enforcing consistency)
- all removed values could not be part of any solution (maintaining equivalence)

Arc Consistency

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Example (Arc consistency)

- Variables x, y with domains $D_x = D_y = \{1, 2, 3\}$.
- $C = \{< x, y >, R_{x,y} = x < y\}$
- D_x and D_y are not arc consistent with $R_{x,y}$
- $D'_x = \{1, 2\}$ $D'_y = \{2, 3\}$ are arc consistent
- $D''_x = \{1\}$ $D''_y = \{2\}$ are arc consistent but...

Constraint propagation for arc consistency

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CP for arc consistency

- If a variable x_i is not arc consistent w.r.t. x_j :
 - remove all values from D_i that does not have a matching value in x_j
- D'_i contains only values that satisfy binary constraints (enforcing consistency)
- all removed values could not be part of any solution (maintaining equivalence)

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Arc Consistency

- Network $\mathcal{R} = \langle X, D, C \rangle$
- $x_i, x_j \in X$
- x_i arc consistent w.r.t. x_j iff
 - $\forall a_i \in D_i \exists a_j \in D_j | (a_i, a_j) \in R_{x_i, x_j}$
- R_{x_i, x_j} is arc consistent iff x_i arc consistent w.r.t. x_j and x_j arc consistent w.r.t. x_i
- \mathcal{R} is arc consistent iff all its constraints are arc consistent

Revise Procedure

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Revise proc.

Algorithm 1 Revise((x_i, x_j))

Require: R_{x_i, x_j}, D_i, D_j

Ensure: D_i such that x_i is arc consistent w.r.t. x_j

for all $a_i \in D_i$ **do**

if $\neg \exists a_j \in D_j | (a_i, a_j) \in R_{x_i, x_j}$ **then**

 delete a_i from D_i

end if

end for

Equivalent to $R_{xy} \leftarrow R_{xy} \cap \pi_{xy}(R_{xz} D_z R_{zy})$

Revise Procedure for Networks

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Revise for Network

```
for all  $x_i \in X$  do  
  for all  $R_{x_i, x_j} \in C$  do  
    Revise( $(x_i), x_j$ );  
    Revise( $(x_j), x_i$ );  
  end for  
end for
```

- This algorithm does not work!
- Revising arc consistency on a variable might make another variable not-arc consistent

Revising Networks

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Example (Revise for Network)

- Variables x, y, z with domains
 $D_x = \{0, 1, 2, 3\}, D_y = \{1, 2\}, D_z = \{0, 1, 2\}$.
- $C_{x,y} = \{ \langle x, y \rangle, R_{x,y} = x < y \},$
 $C_{z,x} = \{ \langle z, x \rangle, R_{z,x} = z < x \}$

Revising Networks

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An algorithm that does work!

AC-1

Require: $\mathcal{R} = \langle X, D, C \rangle$

Ensure: \mathcal{R}' the loosest arc consistent network for \mathcal{R}

repeat

for all Pairs x_i, x_j that participate in a constraint **do**

 Revise($(x_i), x_j$);

 Revise($(x_j), x_i$);

end for

until no domain is changed

■ This algorithm does work!

Inconsistent Networks

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AC-1 always terminate

- If we do not change any domain then we stop and \mathcal{R} is AC
- If we remove a value we make at least one domain smaller
- If a domain is empty the network is inconsistent: we can not find any solution

Inconsistent Networks: Example

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Example

Example

- Variables: $\{x, y, z\}$, domains $D_x = D_y = D_z = \{1, 2, 3\}$
- Constraints $\{x < y, y < z, z < x\}$
- apply AC-1

Computational complexity of AC-1

Comp. complexity

AC-1 is $O(nek^3)$

- n : nodes, e : edges, k : max number of values of a domain
- each cycle: ek^2 operations
- worst case we delete 1 element from one domain at each cycle
- we can have at most nk cycles

Improving AC-1: AC-3

AC-3

Require: $\mathcal{R} = \langle X, D, C \rangle$

Ensure: \mathcal{R}' the loosest arc consistent network for \mathcal{R}

for all every pairs (x_i, x_j) that participate in a constraint

$R_{x_i, x_j} \in \mathcal{R}$ **do**

$Q \leftarrow Q \cup \{(x_i, x_j), (x_j, x_i)\}$

end for

while $Q \neq \{\}$ **do**

pop (x_i, x_j) from Q

REVISE((x_i, x_j))

if D_i changed **then**

$Q \leftarrow Q \cup \{(x_k, x_i), k \neq i, k \neq j\}$

end if

end while

AC-3 Example

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AC-3

- Variables x, y, z , domains $D_x = D_z = \{2, 5\}$, $D_y = \{2, 4\}$
- Constraints: $R_{x,z} = \{a_x, a_z, |(a_x \bmod a_z = 0)|\}$
 $R_{y,z} = \{a_y, a_z, |(a_y \bmod a_z = 0)|\}$
- Run AC-3

AC-3 Computational Complexity

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Comp. Complexity

- $O(ek^3)$
- Revise for each couple is $O(k^2)$
- worst case we evaluate $2ek$
- because we can put back each couple at most k times

Distributed Arc Consistency

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AC-1 can be distributed

- Each node a computer, they can send messages to **neighbours**
- Each computer knows only its direct neighbours and shared constraints
- $\text{Revise} = D_i \leftarrow D_i \cap \pi_i(R_{ij} \bowtie D_j)$
- Node j sends a message to i : $h_{j \rightarrow i} = \pi_i(R_{ij} \bowtie D_j)$
- Node i computes $D_i \leftarrow D_i \cap h_{j \leftarrow i}$ for each message received by its neighbours

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Empty Domain and Arc Consistency

- Arc consistency + empty domain \rightarrow inconsistent problem
- Arc consistent + all domains are not empty \nrightarrow consistent problem
- Arc consistency is not complete
 - It checks only single (binary) constraints and single domain constraint

Example: incompleteness of AC for consistency

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Example

Binary Graph Colouring

- Variables: x, y, z Domain: $D_i = \{R, Y\}$
- Constraints: $x \neq y, y \neq z, z \neq x$

Exercise

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Exercise 1

Consider the following network:

- Variables: $\{X, Y, Z, W\}$, Domain $D_i = \{0, 1, 2\}$
- Constraints: $X < Y$, $Z = X$, $Z < W$, $W < Y$

describe an execution of AC-3. Is the resulting network arc consistent ? Is the resulting network consistent ? Motivate your answers.