

On vortex knots and unknots

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Mathematical Models of Quantum Fluids,
Geometrical Analitical and Computational Aspects

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Fluid flow evolution

We consider a *homogeneous, incompressible fluid* in $\mathbb{R}^3$:

$$\text{velocity field } \mathbf{u} = \mathbf{u}(\mathbf{X}, t) : \begin{cases} \nabla \times \mathbf{u} = \boldsymbol{\omega} \\ \nabla \cdot \mathbf{u} = 0 \\ \mathbf{u} = 0 \text{ as } \mathbf{X} \rightarrow \infty \end{cases} \quad \text{in } \mathbb{R}^3$$

- Fluid motion is governed by:

$$\text{Euler equations} \quad \frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\frac{1}{\rho} \nabla p \quad (1)$$

- Under Euler equations **topology is conserved**.

- Kinetic energy** $T = \frac{1}{2} \rho \int_V |\mathbf{u}|^2 dV = cst;$
- Kinetic helicity** $H = \int_V \mathbf{u} \cdot \boldsymbol{\omega} dV = cst;$
- Vortex circulation** $\Gamma = cst;$
- topological quantities:** knot type, crossing number, linking numbers.



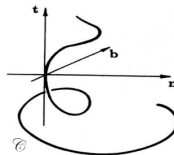
Biot-Savart Law

- Let $\mathcal{C}_t$ be a smooth **space curve** given by:

$$\mathcal{C}_t : \begin{cases} \mathbf{X}(s, t) := \mathbf{X}_t(s) \\ s \in [0, L] \rightarrow \mathbb{R}^3 \end{cases}$$

- The intrinsic reference on $\mathcal{C}_t$ is given by the **Frenet frame** $\{\hat{\mathbf{t}}, \hat{\mathbf{n}}, \hat{\mathbf{b}}\}$:

$$\begin{cases} \hat{\mathbf{t}} = \mathbf{X}'(s, t) = \frac{\partial \mathbf{X}}{\partial s} \\ \hat{\mathbf{n}} = \frac{\hat{\mathbf{t}}'}{c} \\ \hat{\mathbf{b}} = \hat{\mathbf{t}}' \times \hat{\mathbf{n}} \end{cases}$$



- Let identify $\mathcal{C}_t$ with a thin vortex filament of circulation Γ .
 The vortex line moves with a **self induced velocity**:

Biot-Savart (BS) law

$$\mathbf{u}(\mathbf{X}, t) = \frac{\Gamma}{4\pi} \oint_{\mathcal{C}_t} \frac{\hat{\mathbf{t}} \times (\mathbf{X}(s) - \mathbf{X}(s^*))}{|\mathbf{X}(s) - \mathbf{X}(s^*)|^3} ds \quad (2)$$



Vortex filament motion under the Localized Induction Approximation (LIA)

- The Biot-Savart law can be simplified according to the following:

Asymptotic theory :

$$\left\{ \begin{array}{ll} \omega = \omega_0 \hat{\mathbf{t}} & \omega_0 = \text{constant} \\ \frac{R}{a} = \delta \gg 1 & \text{thin tube approximation} \\ \frac{|X(s_i) - X(s_j)|}{|s_i - s_j|} = o(1) & \text{no self-intersection} \end{array} \right.$$

$\Downarrow$

LIA law $\mathbf{u}_{LIA} = \dot{\mathbf{X}}(s, t) \equiv \frac{\partial \mathbf{X}}{\partial t} = \frac{\Gamma}{4\pi} \ln \delta \, \mathbf{X}' \times \mathbf{X}'' = \frac{\Gamma}{4\pi} \ln \delta \, c \hat{\mathbf{b}}, \quad (3)$

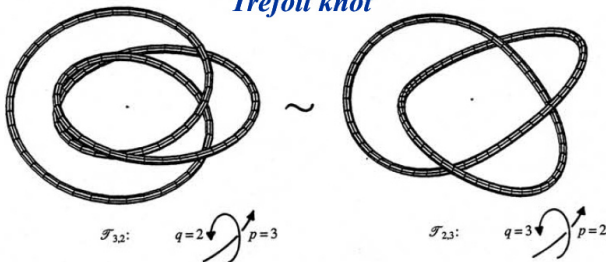


Torus knots

Theorem (Massey, 1967)

A closed, non-self intersecting curve embedded in a torus Π , that cuts a meridian at $p > 1$ points and a longitude at $q > 1$ points (p and q relatively prime integers), is a **non-trivial knot** $\mathcal{T}_{p,q}$, with **winding number** $w = q/p$.

Trefoil knot



- $p > 1$ longitudinal wraps and $q > 1$ meridional wraps;
- For given p, q (p, q coprimes) $\mathcal{T}_{p,q} \sim \mathcal{T}_{q,p}$ **topologically equivalent**.

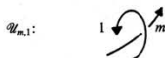
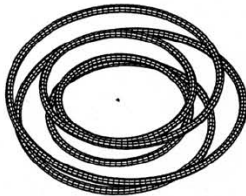


Torus unknots

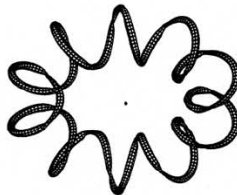
- Case $p = 1$ or $q = 1$:

Unknots

$$\mathcal{U}_{1,m} \sim \mathcal{U}_{m,1} \sim \mathcal{U}_0 \text{ (circle)}$$



$\sim$



Vortex torus knot solution under LIA

Theorem (Kida, 1981)

Let $\mathcal{K}_v$ denote the embedding of a knotted vortex filament in an ideal fluid. If $\mathcal{K}_v$ evolves under LIA, then there exist a class of **steady solutions** in the shape of **torus knots** $\mathcal{K}_v \equiv \mathcal{I}_{p,q}$ in terms of incomplete elliptic integrals:

$$\text{Kida 1981 : } \begin{cases} r^2 = F_r(J) \\ \alpha = F_\alpha(E) \\ z = F_z(\Pi) \end{cases}$$

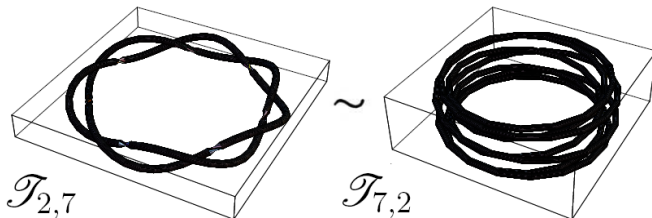
- Solution $\mathcal{I}_{p,q}$ in explicit **analytic closed form**, based on **linear perturbation** from the circular solution $\mathcal{U}_0$ of NLS:

$$\text{Ricca 1993 : } \begin{cases} r = r_0 + \epsilon r_1, \\ \alpha = \frac{s}{r_0} + \epsilon \alpha_1, \\ z = \frac{\hat{t}}{r_0} + \epsilon z_1, \end{cases} \Rightarrow \begin{cases} r = r_0 + \epsilon \sin(w\phi), \\ \alpha = \frac{s}{r_0} + \epsilon \frac{1}{wr_0} \cos(w\phi), \\ z = \frac{\hat{t}}{r_0} + \epsilon \left(1 + \frac{1}{w^2}\right)^{1/2} \cos(w\phi), \end{cases}$$



Theorem (Ricca, 1993)

Let $\mathcal{I}_{p,q}$ denote the embedding of a small-amplitude vortex torus knot $\mathcal{K}_v$ evolving under LIA. $\mathcal{I}_{p,q}$ is *steady* and *stable* under linear perturbation *iff* $q > p$ ($w > 1$).



Definition

A vortex structure is said to be *Lyapunov (structurally) stable* if it evolves under signature-preserving flows that conserve its topology, geometric signature and vortex coherency.

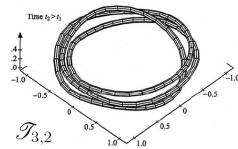
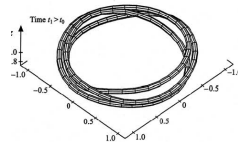
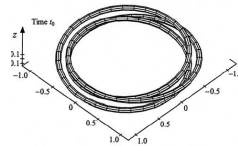
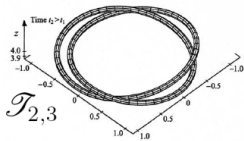
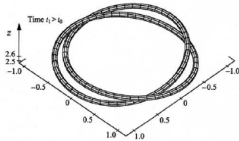
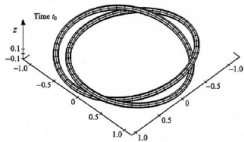


Numerical study of evolution of vortex knots

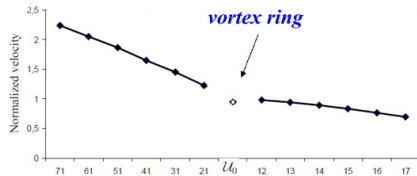
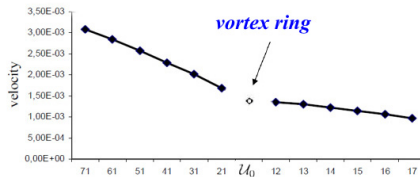
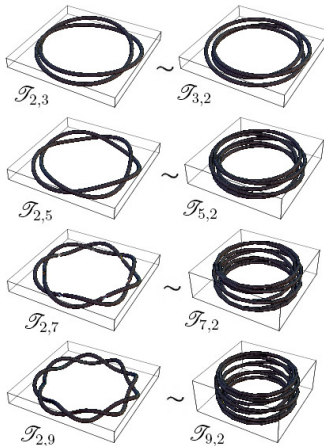
- The evolution of the vortex is obtained by **integrating** the equation of motion forward in time at each point from the initial vortex configuration;
- Typical **time step**: $\Delta t \in [0.001, 0.1]$ chosen in relation of value $N \in [100, 400]$ = number of sub-division of initial vortex configuration;
- The **calculation** is **non-dimensionalized**: $r_0 = 1$, $\Gamma = 1$, $\epsilon_0 = 0.1$;
- T_{tot} : **time elapsed** at the occurrence of the first knot self-intersection;
- D_{tot} : **distance travelled** in time T_{tot} ;
- **Convergence** tested both in **space** and **time** (independently from N and Δt);
- **Computation** performed on Intel(R) Core(2) Duo CPU T7300 2.00 GHZ, RAM 1.99 GB;



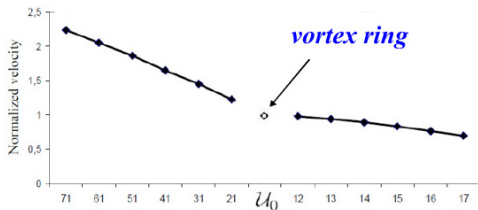
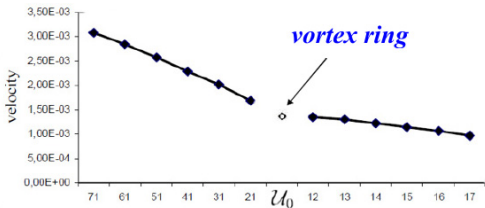
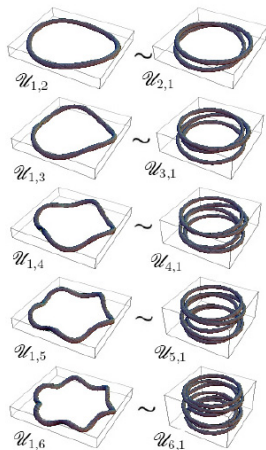
Torus knots $\mathcal{T}_{2,3}$ and $\mathcal{T}_{3,2}$ under Biot-Savart (BS) law



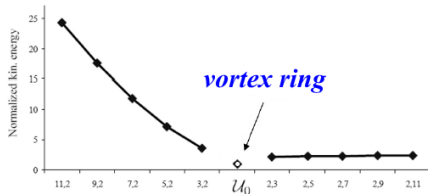
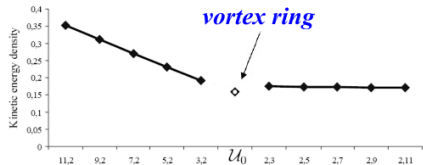
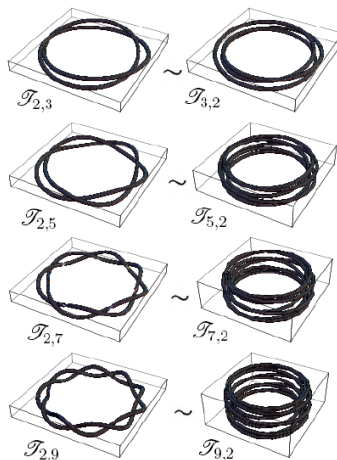
BS evolution of vortex knots velocity



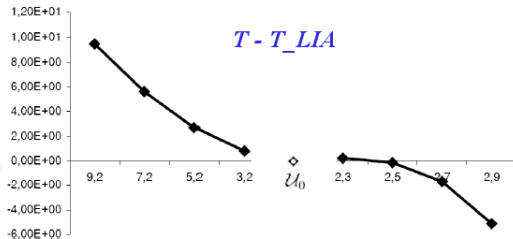
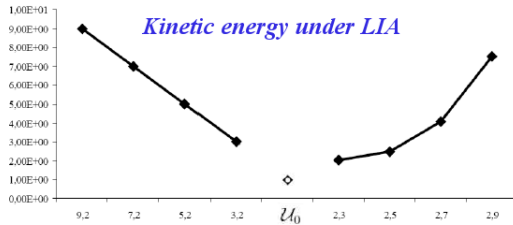
BS evolution of vortex unknots velocity



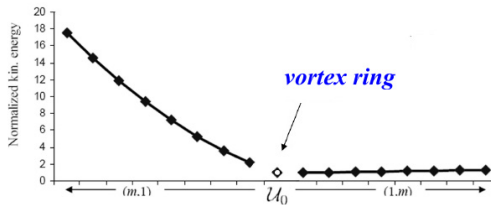
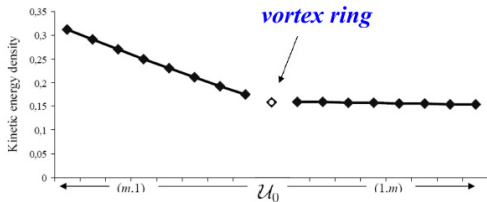
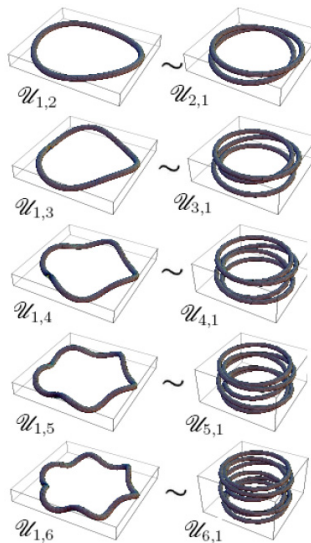
BS evolution of vortex knots kinetic energy



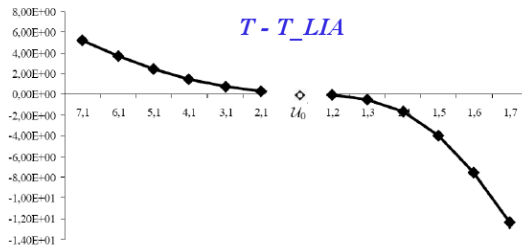
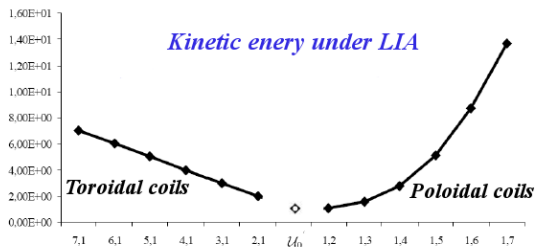
LIA evolution of vortex knots kinetic energy



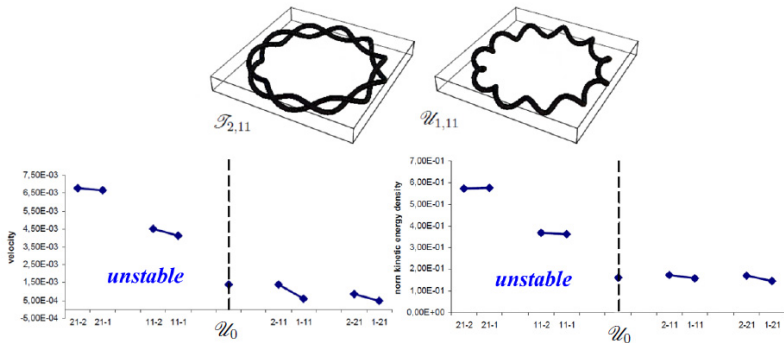
BS evolution of vortex unknots kinetic energy



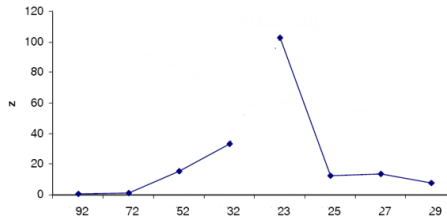
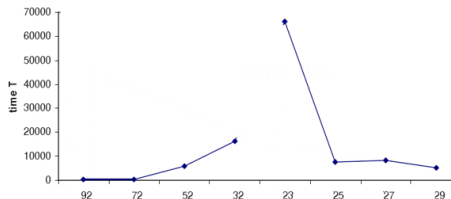
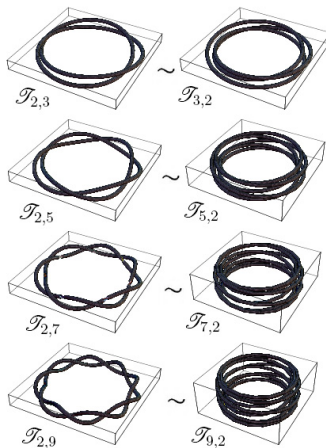
LIA evolution of vortex unknots kinetic energy



Role of topology in global dynamics



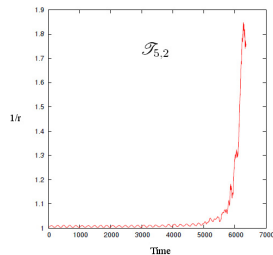
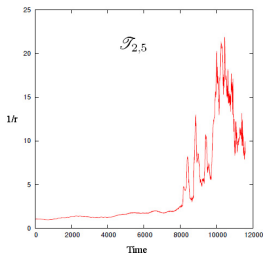
Stability of vortex knots



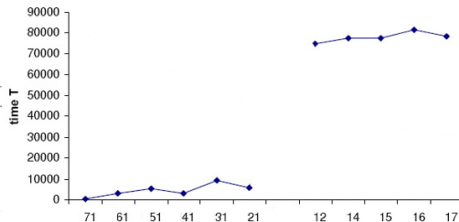
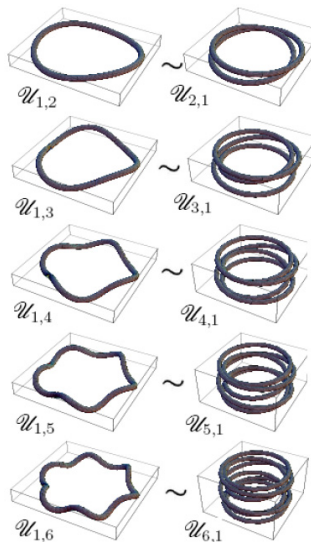
Stability of vortex knots

- the space travelled before a reconnection event decreases with increasing complexity;
- $\mathcal{T}_{p,2}$ is **faster** than its isotope $\mathcal{T}_{2,p}$;
- $\mathcal{T}_{p,2}$ is **not** necessarily **less stable** than its isotope $\mathcal{T}_{2,p}$;

p	q	N	L	z	t
2	5	385	12,86	0,1414588451E+02	0,8761708008E+04
5	2	219	31,33	0,1548856926E+02	0,5851551758E+04

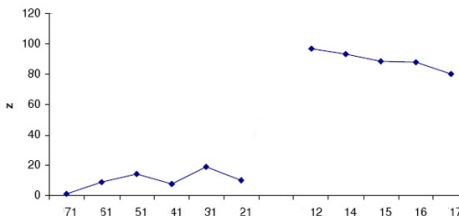


Stability of vortex unknots



toroidal coils

poloidal coils



Future work

Future work

- Role of **chirality** under LIA and BS evolution;
- **Structural stability** under LIA and BS law.
- **vortex bundles**.

References

-  Maggioni, F., Alamri, S., Barenghi, C.F. & Ricca R.L. Kinetic energy of vortex knots and unknots. *Il Nuovo Cimento C*, **32**, 1, 133-142.
-  Ricca, R.L. (1993) *Torus knots and polynomial invariants for a class of soliton equations*. Chaos **3**, 83-91. [1995 Erratum. Chaos **5**, 346.]
-  Ricca, R.L., Samuels, D.C. & Barenghi, C.F. (1999) *Evolution of vortex knots*. J. Fluid Mech **391**, 22-44.

